

Android Jelly Bean BSP Porting Guide
: MSM8960, Fusion Chipset



ANDROID

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<Jelly Bean File Download>

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Jelly Bean File Download
from Code Aurora Forum

1. Jelly Bean Code Download & Build(1) – Android full source

1) Jelly Bean code download

```
# curl https://dl-ssl.google.com/dl/googlesource/git-repo/repo > ~/CAF/bin/repo
# export PATH= ~/CAF/bin:$PATH
# repo init -u git://codeaurora.org/platform/manifest.git -b jb -m M8960AAAAANLYA2205.xml
--repo-url=git://codeaurora.org/tools/repo.git
# repo sync -j4
```

(*) *vendor 디렉토리를 제외하면, 상용 버전을 위한 코드와 동일함.*

2) Jelly Bean build

```
# source build/envsetup.sh
# choosecombo
    1          ← release
    msm8960
    eng
# make -j4
    ➔ out/target/product/msm8960/emmc_appsboot.mbn, boot.img, cache.img,
    persist.img, ramdisk.img, recovery.img, system.img, userdata.img
```

For more information, see the following site.

➔ <https://www.codeaurora.org/xwiki/bin/QAEP/>

1. Jelly Bean Code Download & Build(2) – *msm kernel code*

1) Kernel code download

```
# git clone git://codeaurora.org/kernel/msm.git
# cd msm
# git branch
  *android-msm-2.6.29
  jb_chocolate
  msm-3.4
# git checkout jb_chocolate
or
# git checkout msm-3.4
```

*Kernel 만 download 할 경우의 예이며,
앞서 Android를 download 받았을 경우,
불필요한 작업임^^*

2) Kernel build

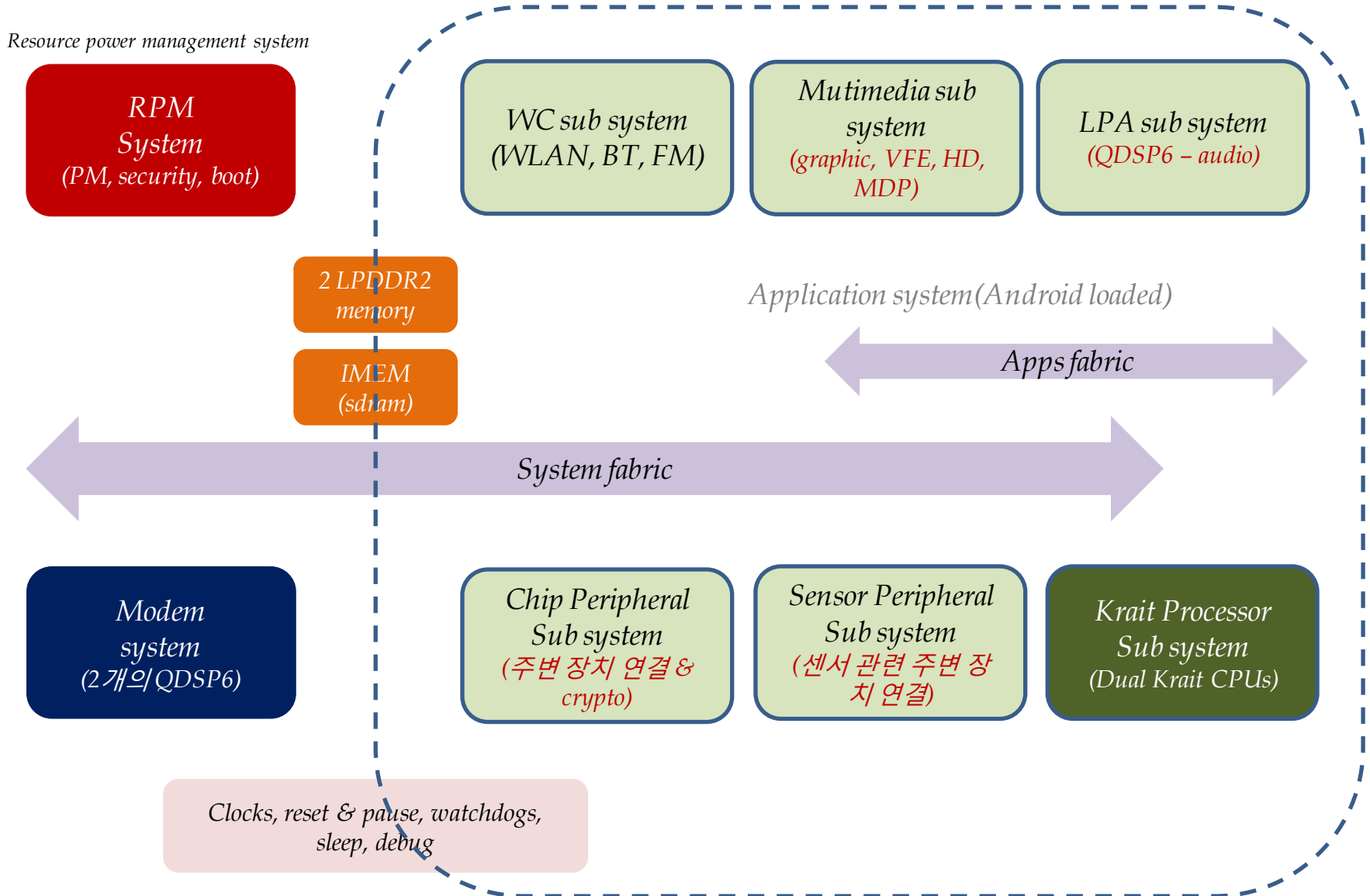
```
# export PATH=$(YOUR_HOME)/mydroid_jb/prebuilt/linux-x86/toolchain/arm-eabi-4.4.3/bin:$PATH
# make ARCH=arm CROSS_COMPILE=arm-eabi- msm8960-perf_defconfig
# make ARCH=arm CROSS_COMPILE=arm-eabi- menuconfig
# make ARCH=arm CROSS_COMPILE=arm-eabi- zImage
# make ARCH=arm CROSS_COMPILE=arm-eabi- modules
```

For more information, See the following site.

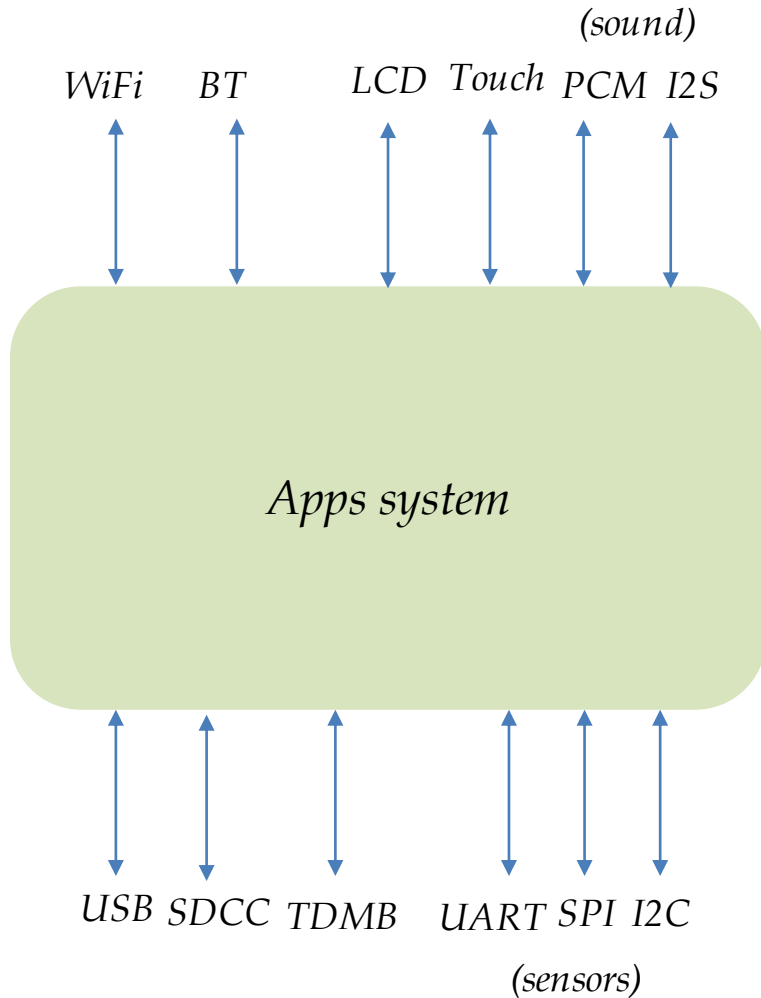
➔ <https://www.codeaurora.org/gitweb/quic/la/?p=kernel/msm.git;a=heads>

Case1: MSM8960

2. MSM8960 Chipset Overview(1)



2. MSM8960 Chipset Overview(2)

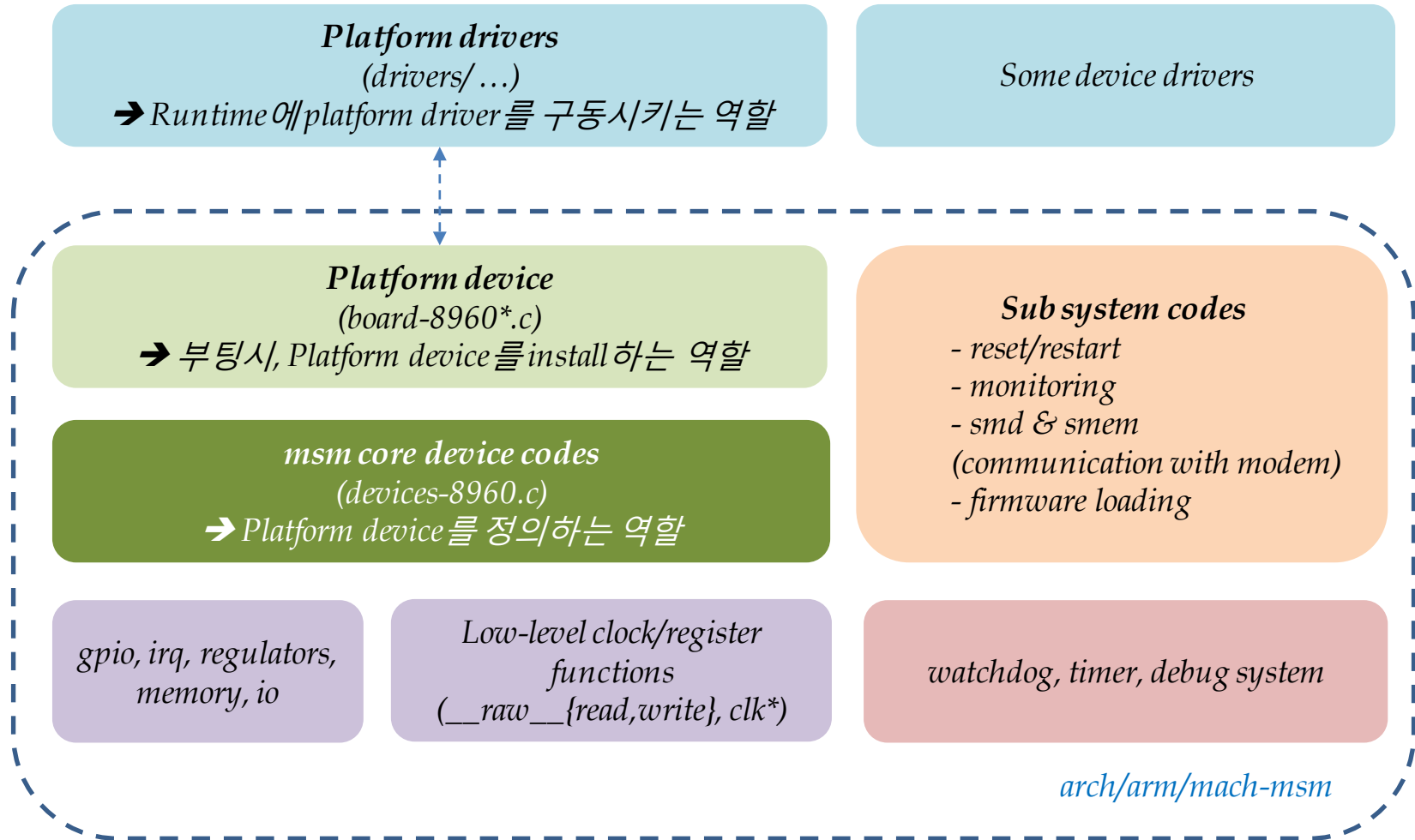


(*) 옆의 그림에서는 실제 연결(통신) 방식과 기능을 편의상 서로 혼용해서 사용하였음.

→ 즉, WiFi는 SDIO, BT는 UART를 사용하나...

(*) 옆의 그림을 그린 이유는, 실제로 kernel code에서 이를 기술해 주고 있기 때문임.

3. MSM8960 Machine Code Review(1)



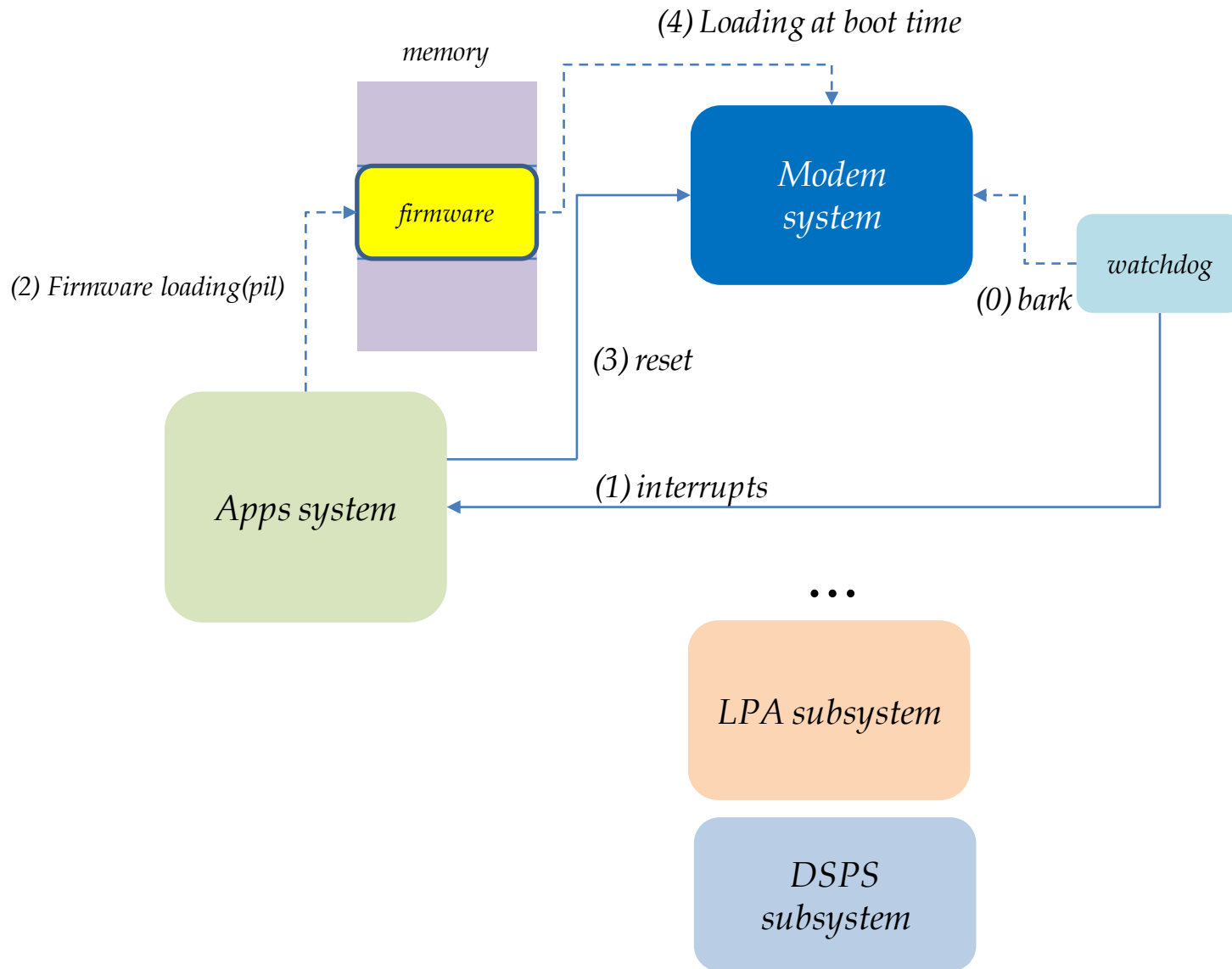
3. MSM8960 Machine Code Review(2)

- 1) CPU 기술(description) → clock...
- 2) bus 기술 → system fabric, apps fabric, clocks ...
- 3) memory 기술 & 사용 관련 정의 → pmem, ion mem 등 할당 ...
- 4) CPU와 주변 sub system과의 관계 기술 → interrupt, reset, communication
- 5) 주변 장치 기술/초기화(i2c, spi, uart, uim, sdcc, usb, ..., gpio, irq, regulators) → GSBI & GPIOMux
- 6) key internal functions 기술 → watchdog, sleep...
- 7) linux driver model 적용(platform device & driver)

3. MSM8960 Machine Code Review(3) – MACHINE_START macro

```
MACHINE_START(MSM8960_CDP, "QCT MSM8960 CDP")
    .map_io = msm8960_map_io,
    .reserve = msm8960_reserve,
    .init_irq = msm8960_init_irq,
    .handle_irq = gic_handle_irq,
    .timer = &msm_timer,
    .init_machine = msm8960_cdp_init,
    .init_early = msm8960_allocate_memory_regions,
    .init_very_early = msm8960_early_memory,
    .restart = msm_restart,
MACHINE_END
```

3. MSM8960 Machine Code Review(4) – *restart subsystem*



3. MSM8960 Machine Code Review(5) - gpiomux/1

<gpio operation 정의>

- `drivers/gpio/gpio-msm-common.c`

→ `msm_gpio_probe()` 함수에서 `gpiochip_add(&msm_gpio_gpio_chip)`을 호출하여 `msm_gpio_gpio_chip`을 등록했으므로, 이후 kernel에서 사용하는 `gpio` 관련 함수 즉, `request`, `free`, `set`, `get`, `direction_input`, `direction_output` 등은 모두 `msm_gpio`에서 새로 정의한 함수를 사용하게 될 것임.

- `drivers/gpio/gpio-msm-v2.c`

- `drivers/gpio/gpiolib.c`

- `drivers/gpio/pm8xxx-gpio.c`

<gpio pin 배치 정의>

- `arch/arm/mach-msm/gpiomux.c`

- `arch/arm/mach-msm/gpiomux-v2.c`

- `arch/arm/mach-msm/board-8960-gpiomux.c`

→ 여기에서 `gpiomux pin` 배치 코드 나열함.

=> See `Documentation/arm/msm/gpiomux.txt`

3. MSM8960 Machine Code Review(6) - gpiomux/2

<gpiomux setting example>

```
struct msm_gpiomux_config gpio123_config __initdata = {
    .gpio = 123,
    .settings = {
        [GPIOMUX_ACTIVE] = {
            .func = GPIOMUX_FUNC_GPIO,
            .drv = GPIOMUX_DRV_2MA,
            .pull = GPIOMUX_PULL_NONE,
            .dir = GPIOMUX_OUT_HIGH,
        },
        [GPIOMUX_SUSPENDED] = {
            .func = GPIOMUX_FUNC_3,
            .drv = GPIOMUX_DRV_8MA,
            .pull = GPIOMUX_PULL_DOWN,
        },
    },
};
```

<gpiomux setting 의미>

- When the system boots, gpio 123 will be put into the SUSPENDED setting.
- When the reference count for gpio 123 rises above 0, the ACTIVE setting will be applied.
- When the reference count falls back to 0, the SUSPENDED setting will be reapplied.

➔ 이렇게 하는(runtime gpio configuration) 이유는 전류 소모를 최대한 줄이기 위함이다!

<초기화- msm8960_init_gpiomux()에서 호출함>

- msm_gpiomux_init() -> memory 할당
- msm_gpiomux_install() -> 해당 gpio pin 주소에 값(drv, func, pull 등의 참조)을 쓰고 있음(초기화 정도)

3. MSM8960 Machine Code Review(7) - GSBI 주변 장치 추가 절차

1) Set the clocks

→ `arch/arm/mach-msm/clock-8960.c`

2) Create a platform device

→ `arch/arm/mach-msm/devices.h`

→ `arch/arm/mach-msm/devices-8960.c`

→ `arch/arm/mach-msm/board-8960.c`

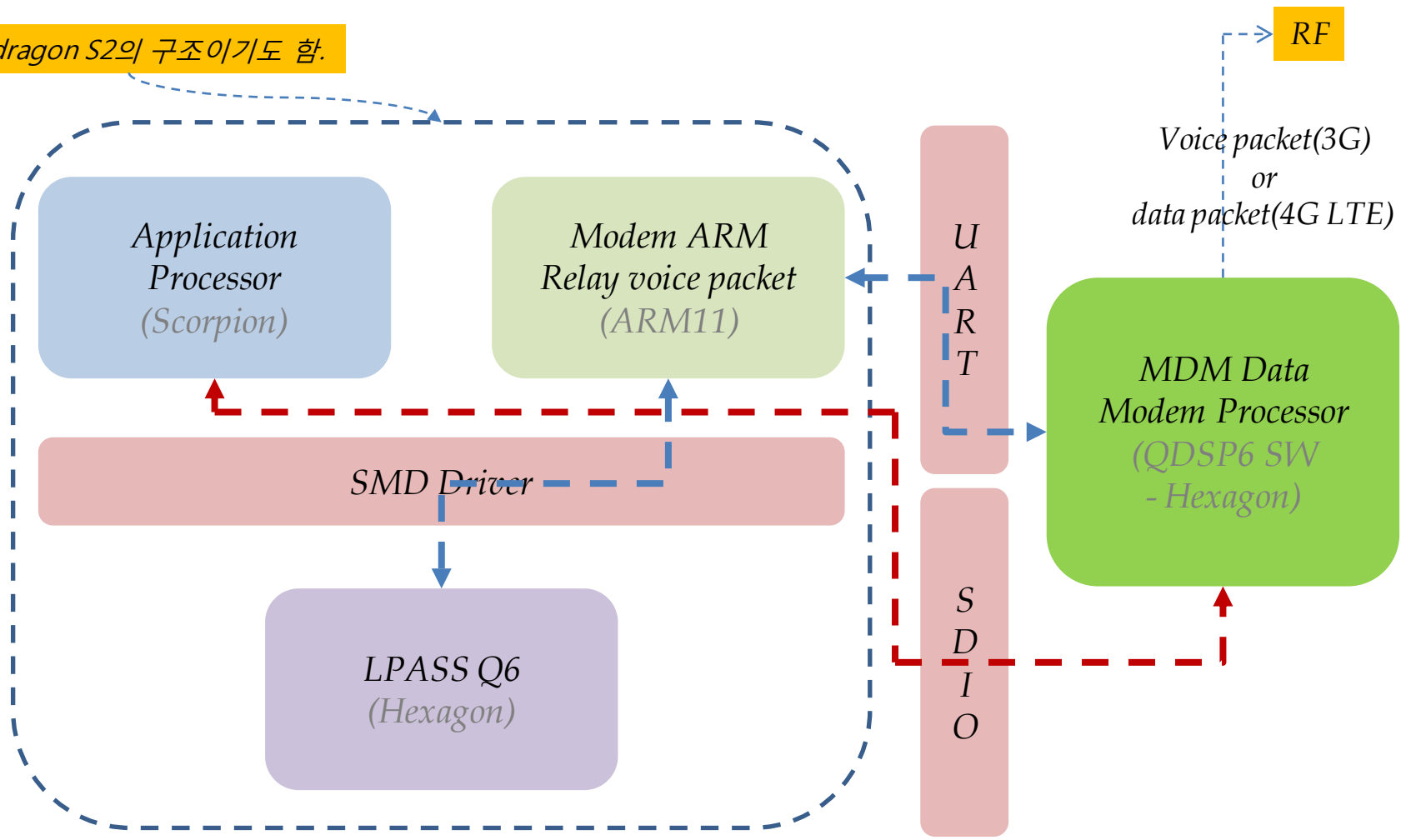
3) Configure GPIO

→ `arch/arm/mach-msm/board-8960-gpiomux.c`

*Case2: APQ/MSM8x60 + MDM9x00
fusion chipset*

4. Fusion Chipset Overview(1)

Snapdragon S2의 구조이기도 함.

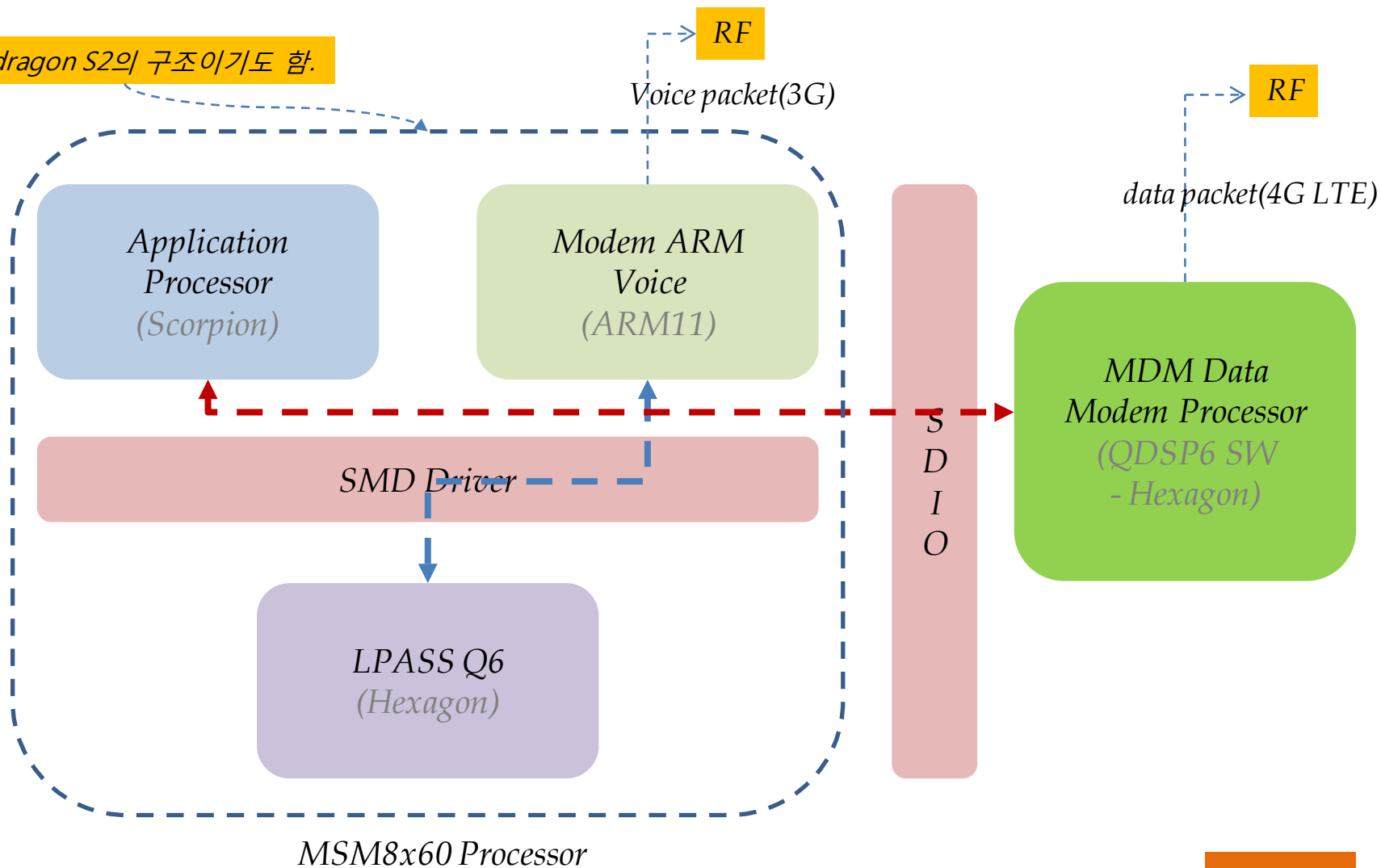


←- - - - -> voice flow
←- - - - -> data flow

CSFB

4. Fusion Chipset Overview(2)

Snapdragon S2의 구조이기도 함.

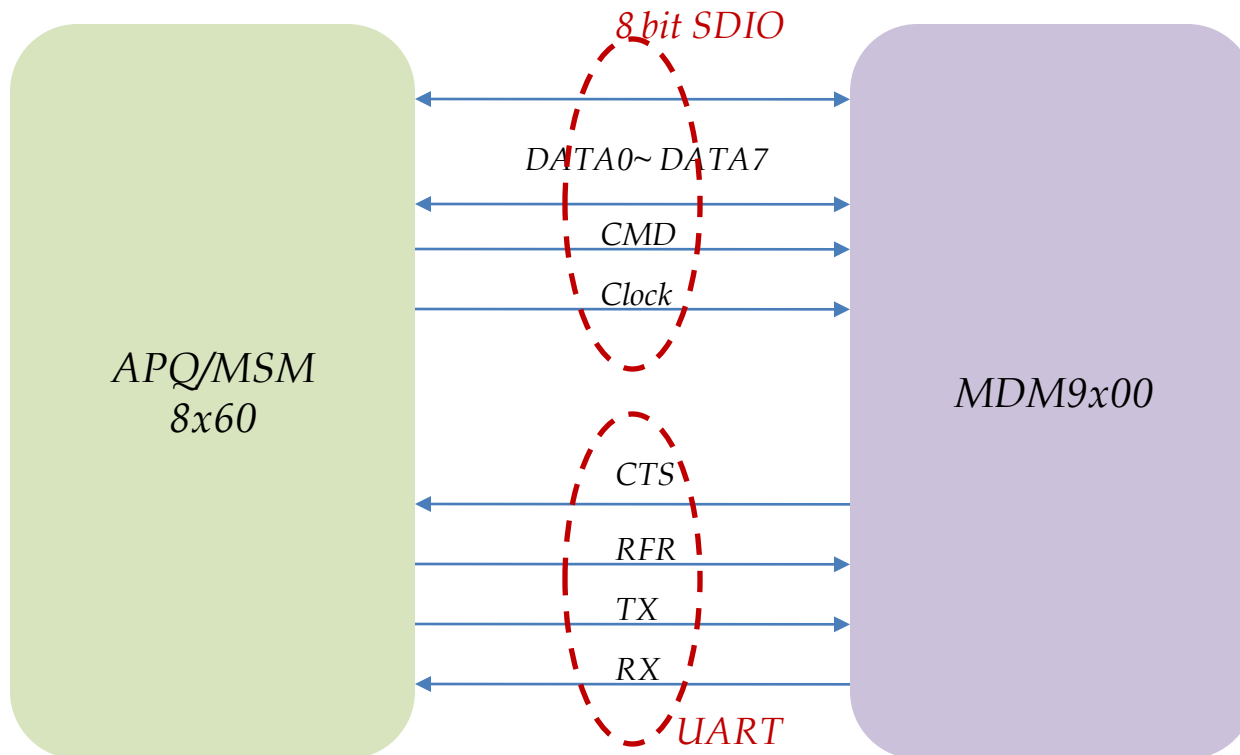


←- - - - -> voice flow
←- - - - -> data flow

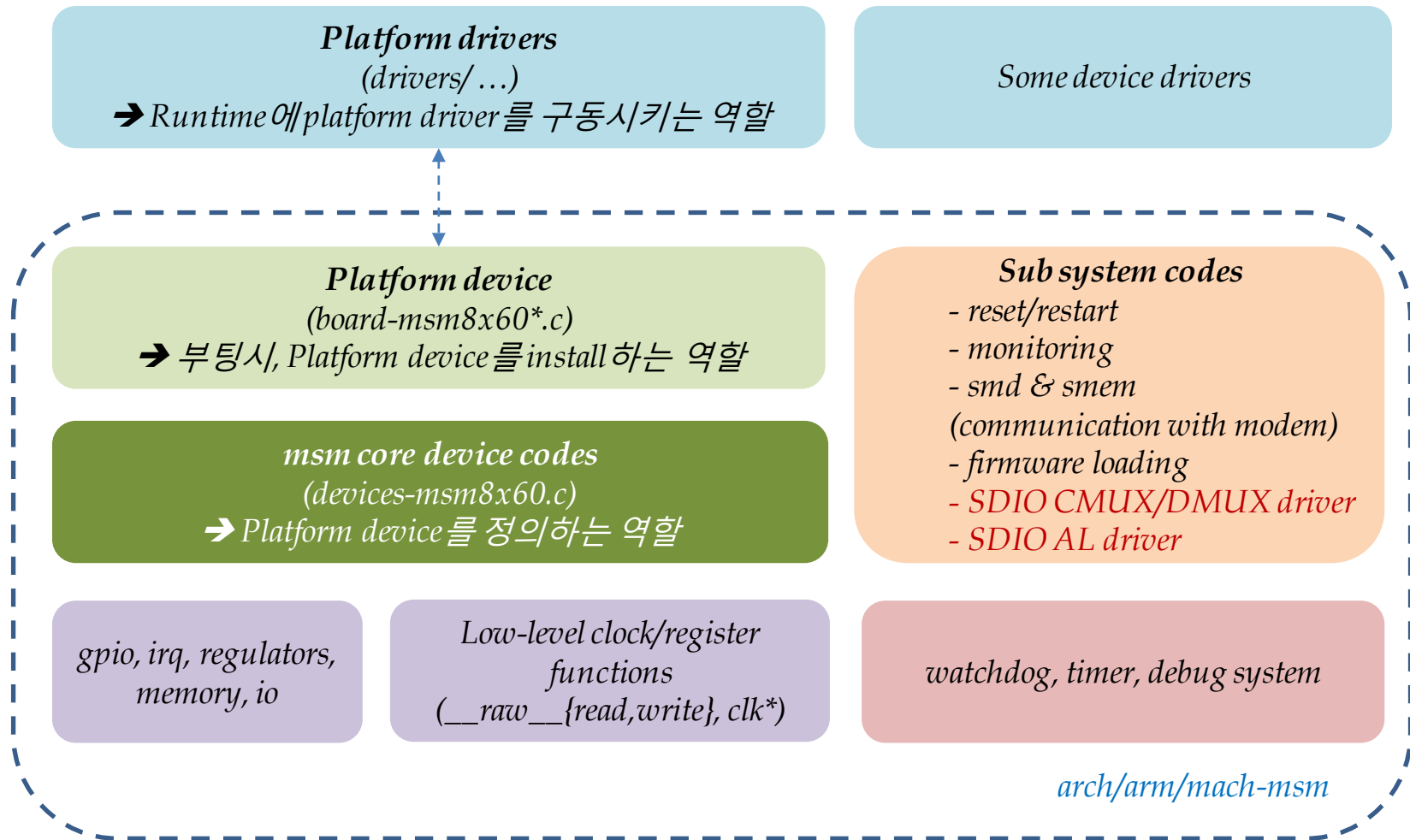
SVLTE

4. Fusion Chipset Overview(3)

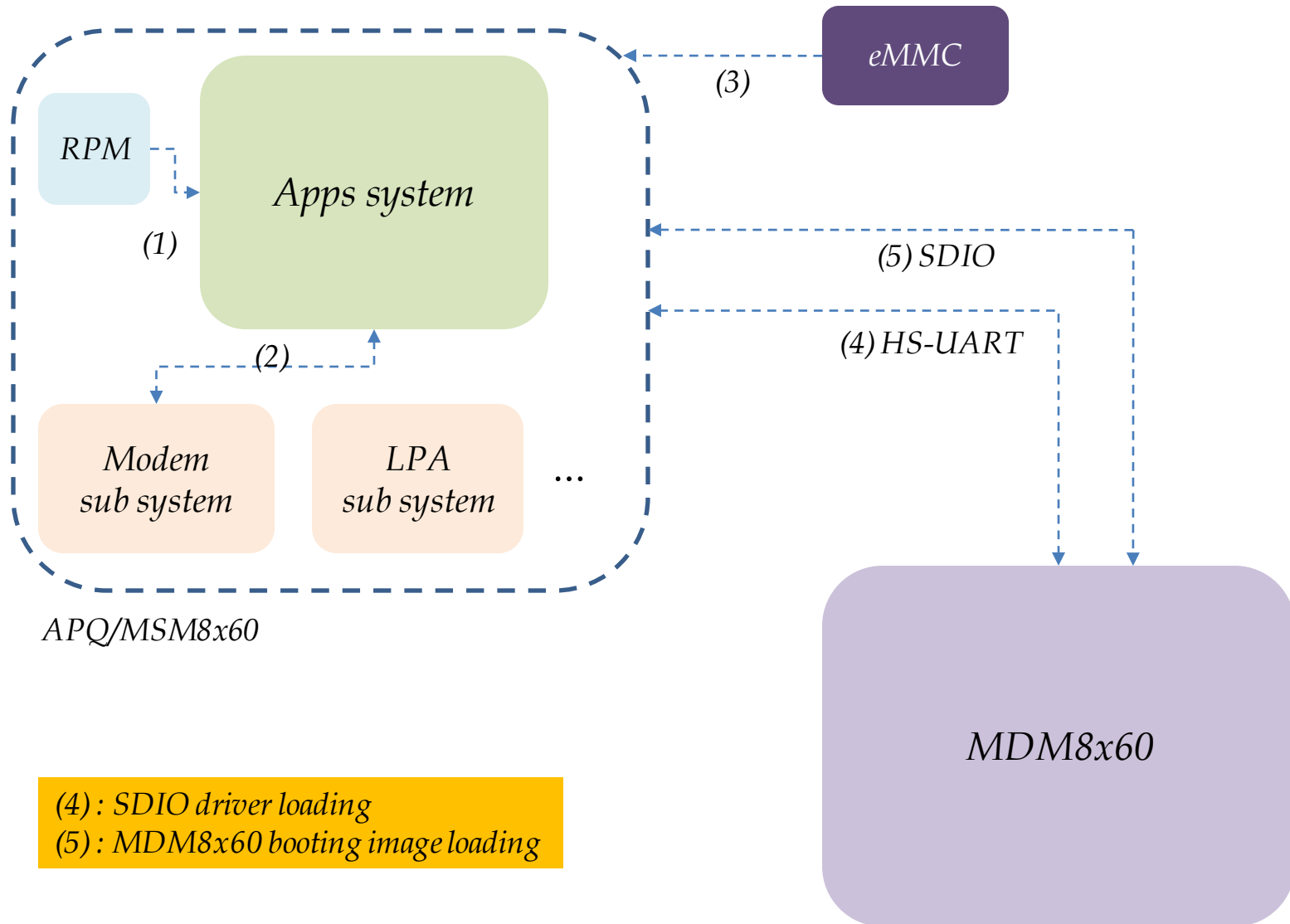
- **SDIO**: QMI, RmNet, RPC, Diag
 - ➔ 주로 LTE data 전송을 위해 사용됨(고속 data 전송).
- **HS-UART**: QMI control, voice, boot
 - ➔ 주로 voice data 를 전송하기 위해 사용됨.



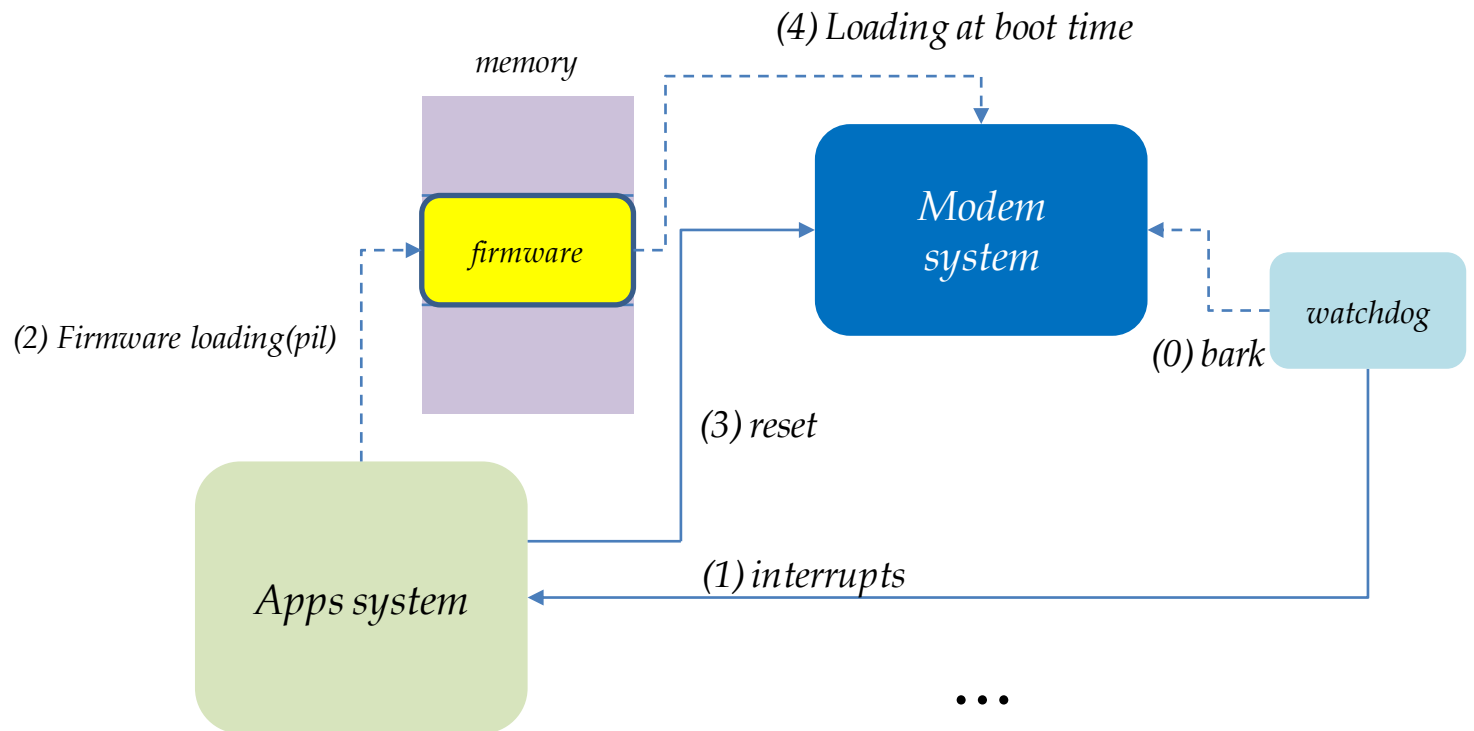
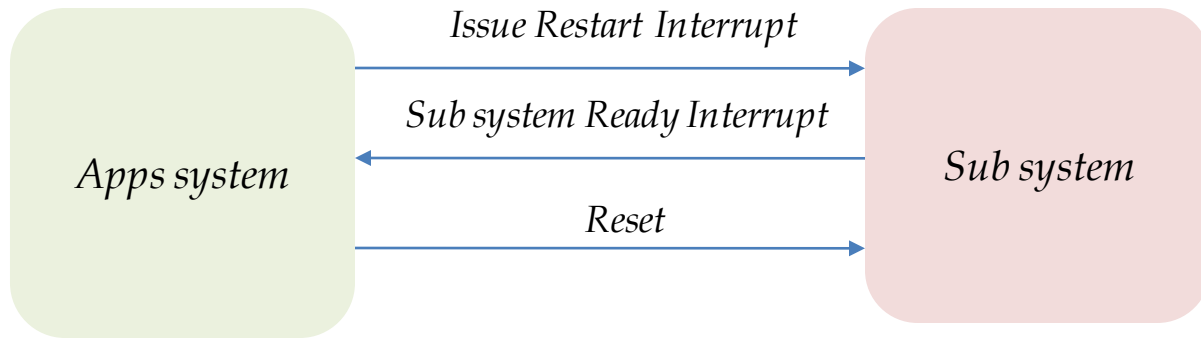
5. APQ/MSM8x60 Machine Code Review



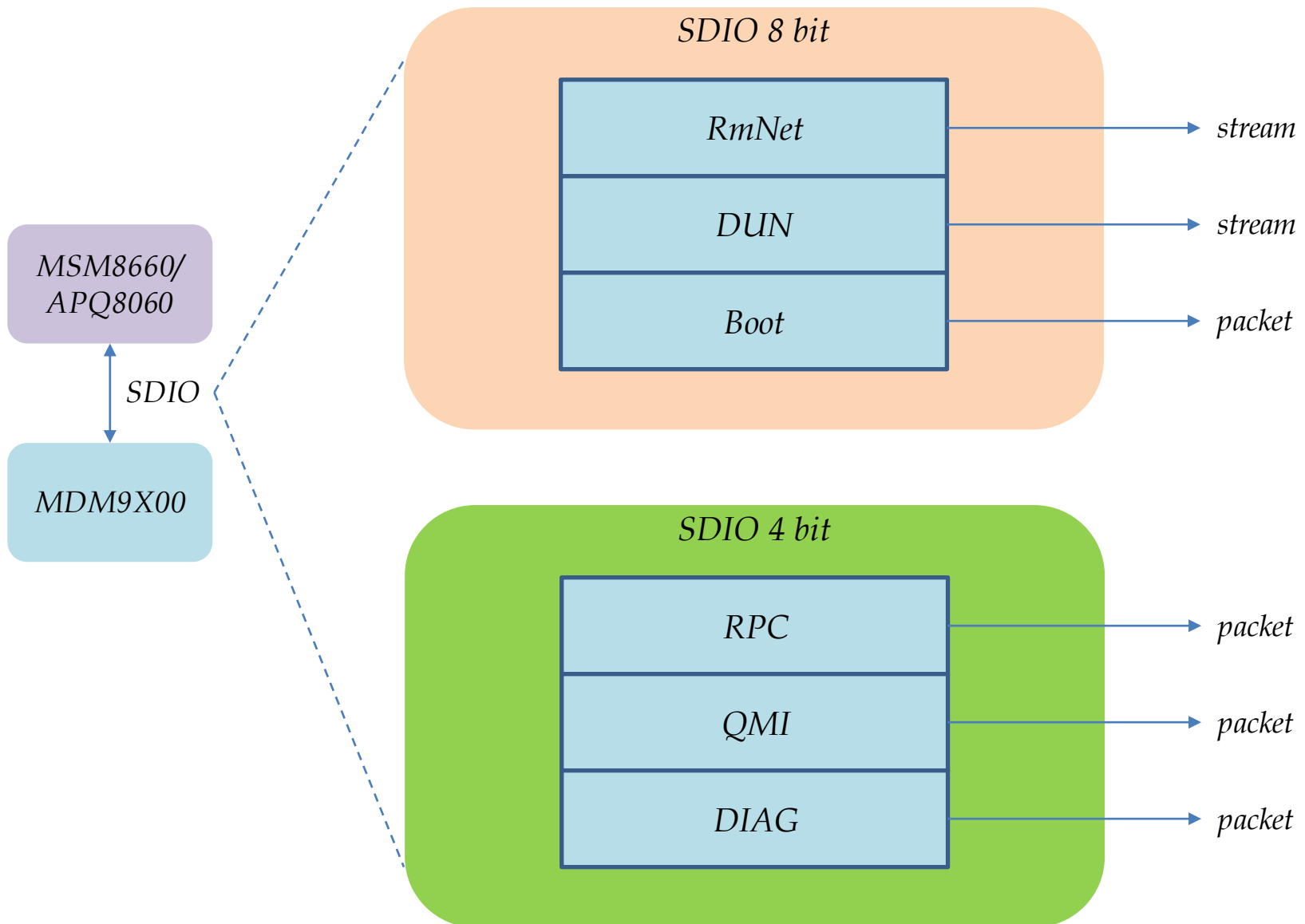
5. APQ/MSM8x60 Machine Code Review – *Boot Flow*



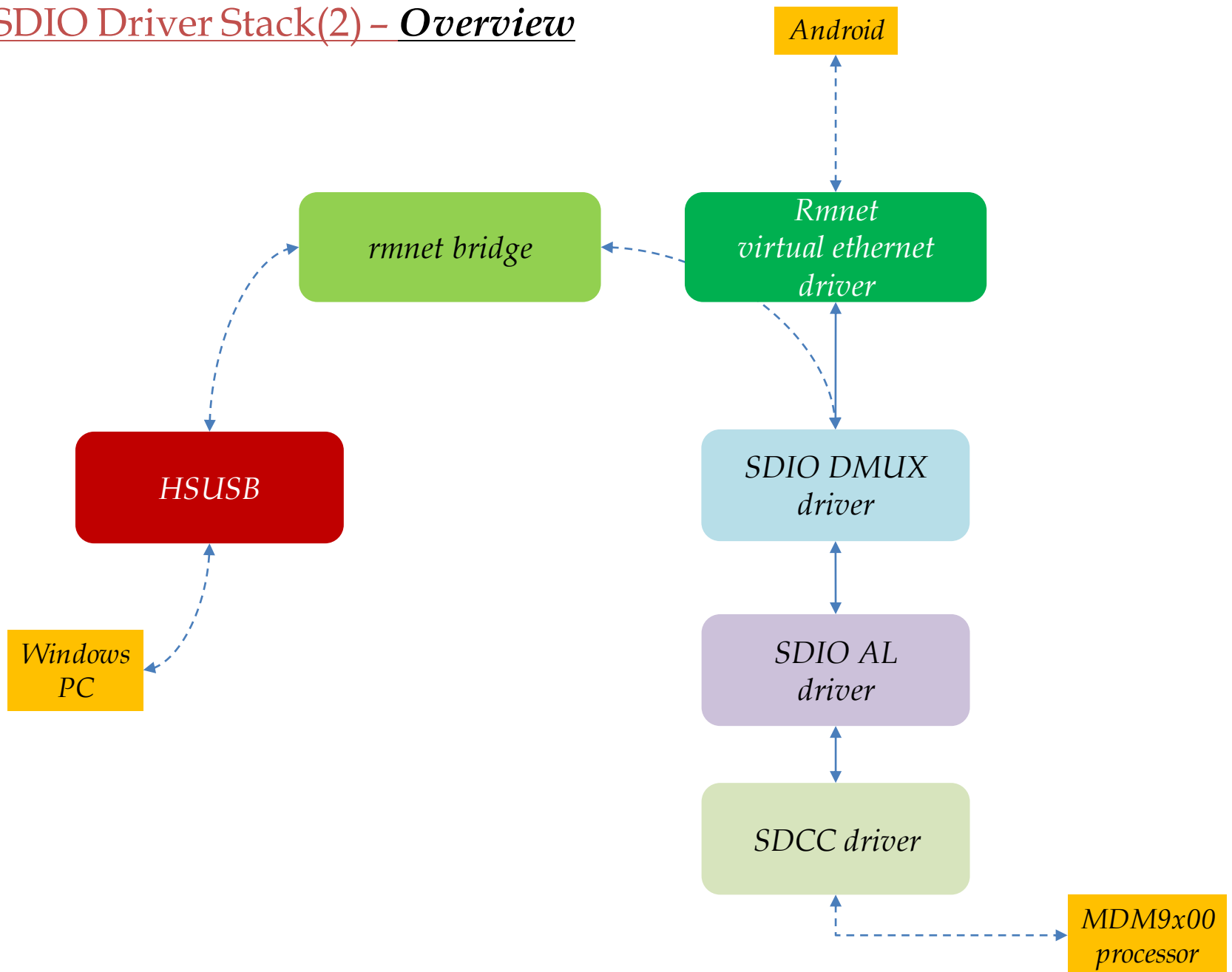
5. APQ/MSM8x60 Machine Code Review – *Sub system Restart*



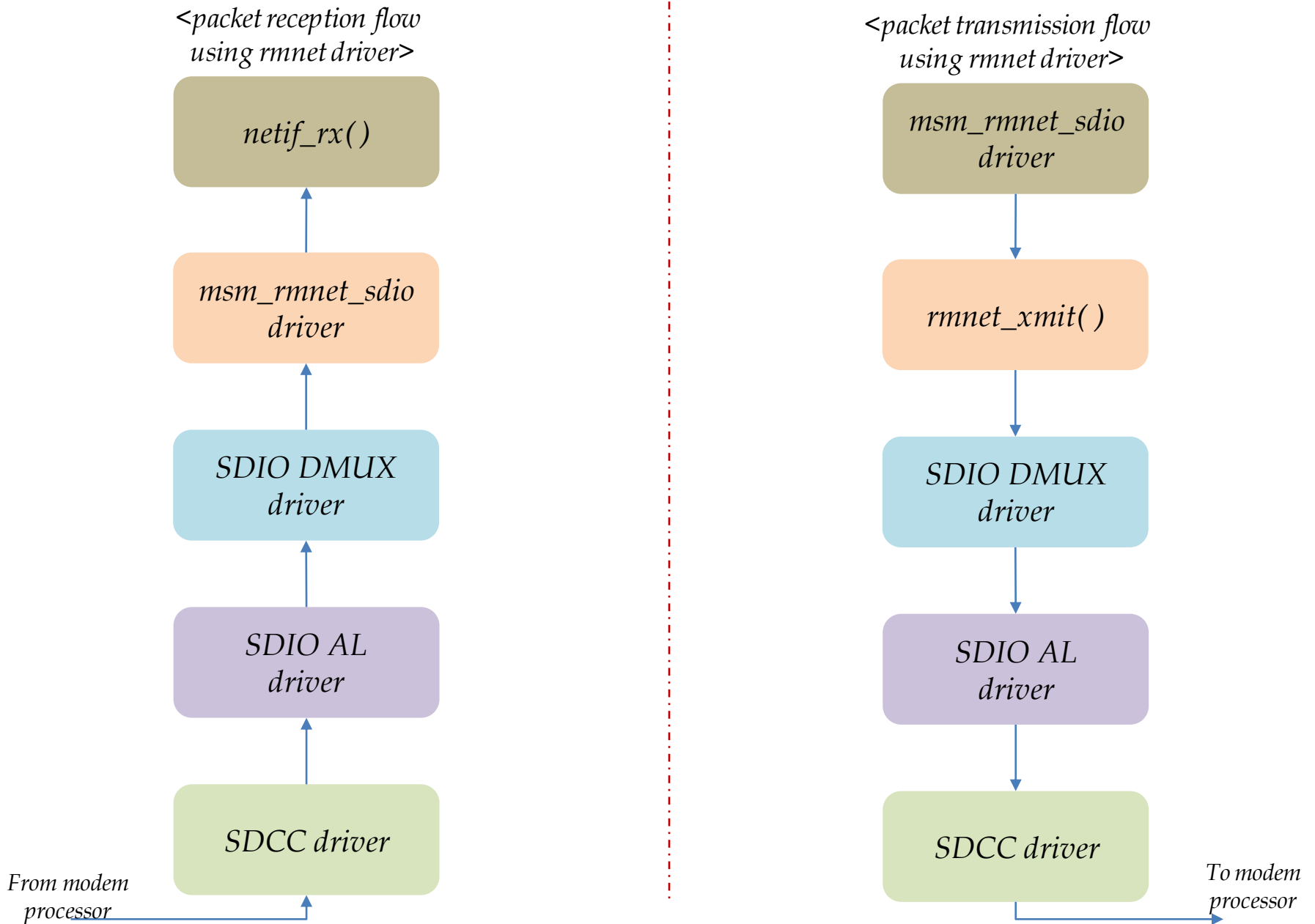
6. SDIO Driver Stack(1) – SDIO 8/4 pins



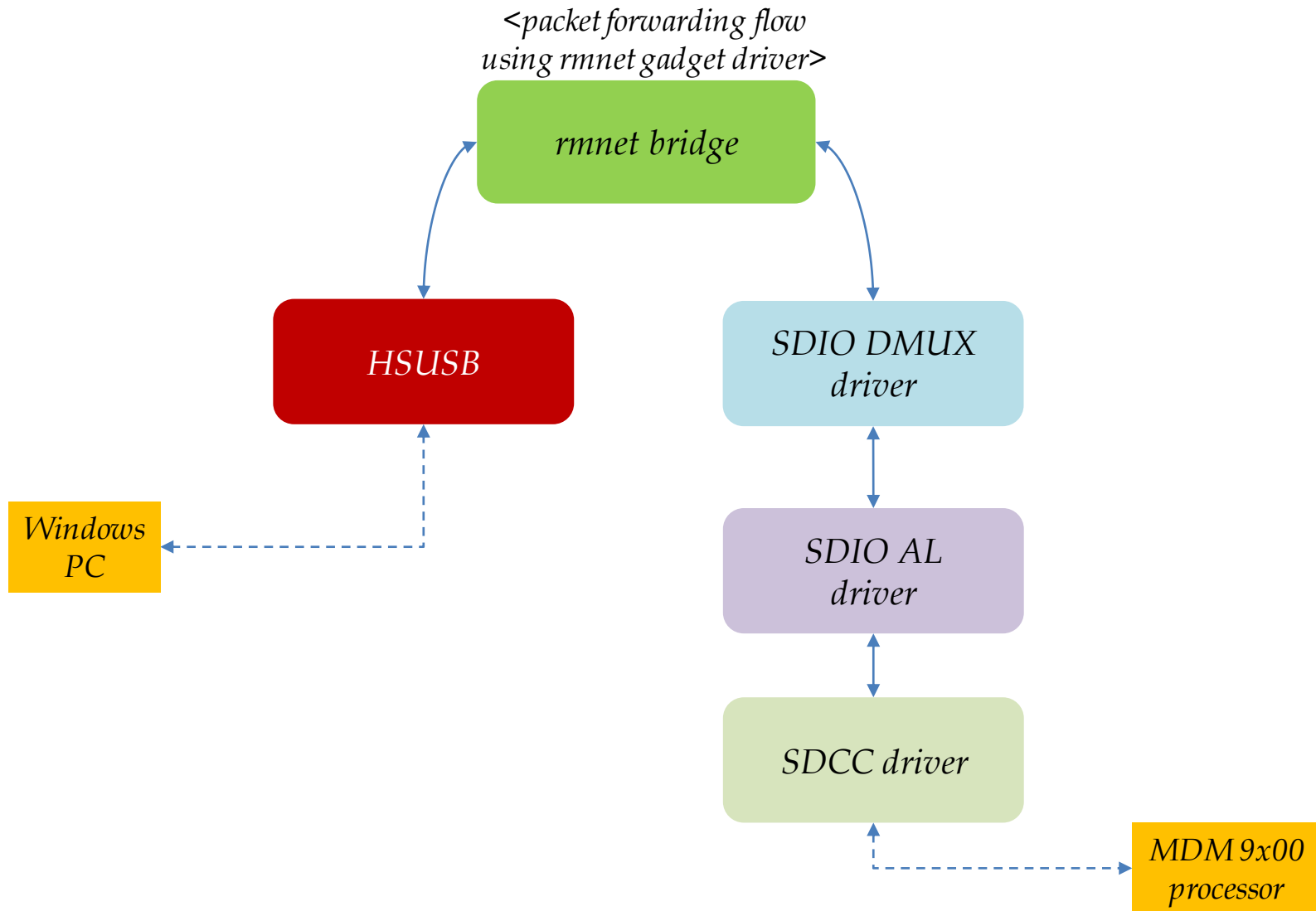
6. SDIO Driver Stack(2) – Overview



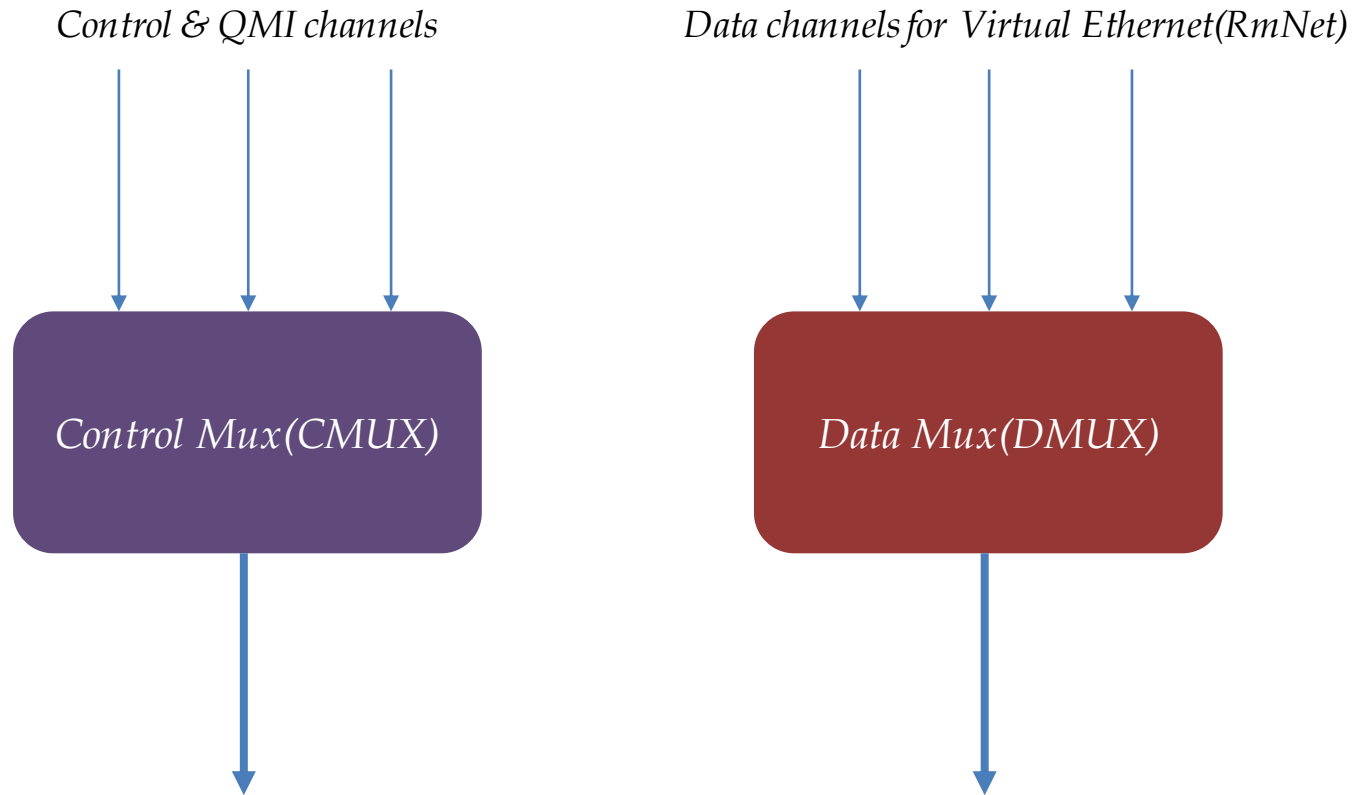
6. SDIO Driver Stack(3) - LTE data packet flow



6. SDIO Driver Stack(4) - *LTE data packet flow under Tethering Env.*



6. SDIO Driver Stack(5) – *Mux Driver*

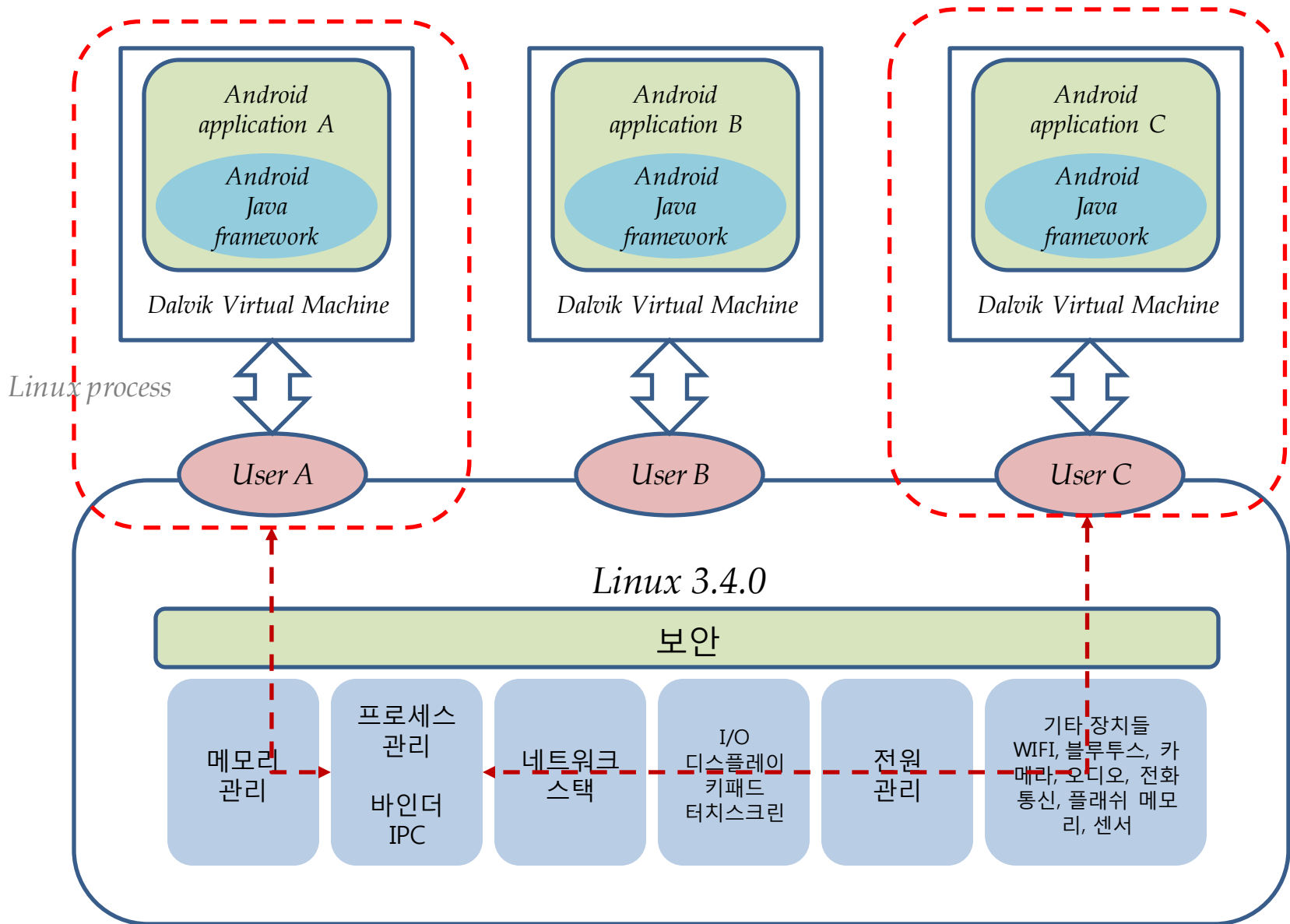


(*) 위의 그림은 MUX를 통해 control 및 data packet이 하나로 묶여 전달되는 것을 그림으로 표현한 것으로, 패킷 수신 시에는 반대의 과정을 거치게 된다.

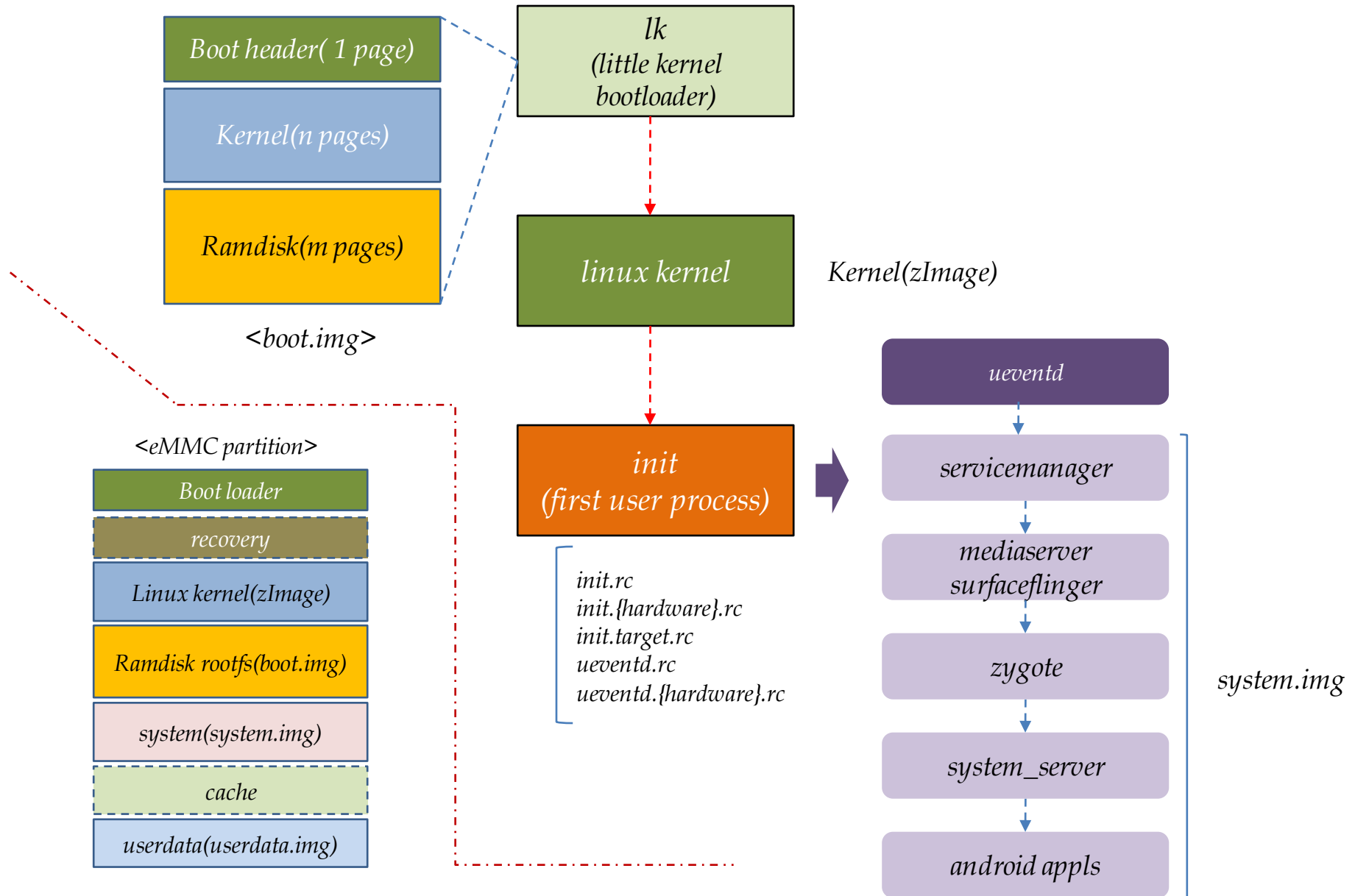
→ framing/deframing, multiplexing of multiple logical SDIO ports over a single SDIO function

Jelly Bean BSP Porting Guide

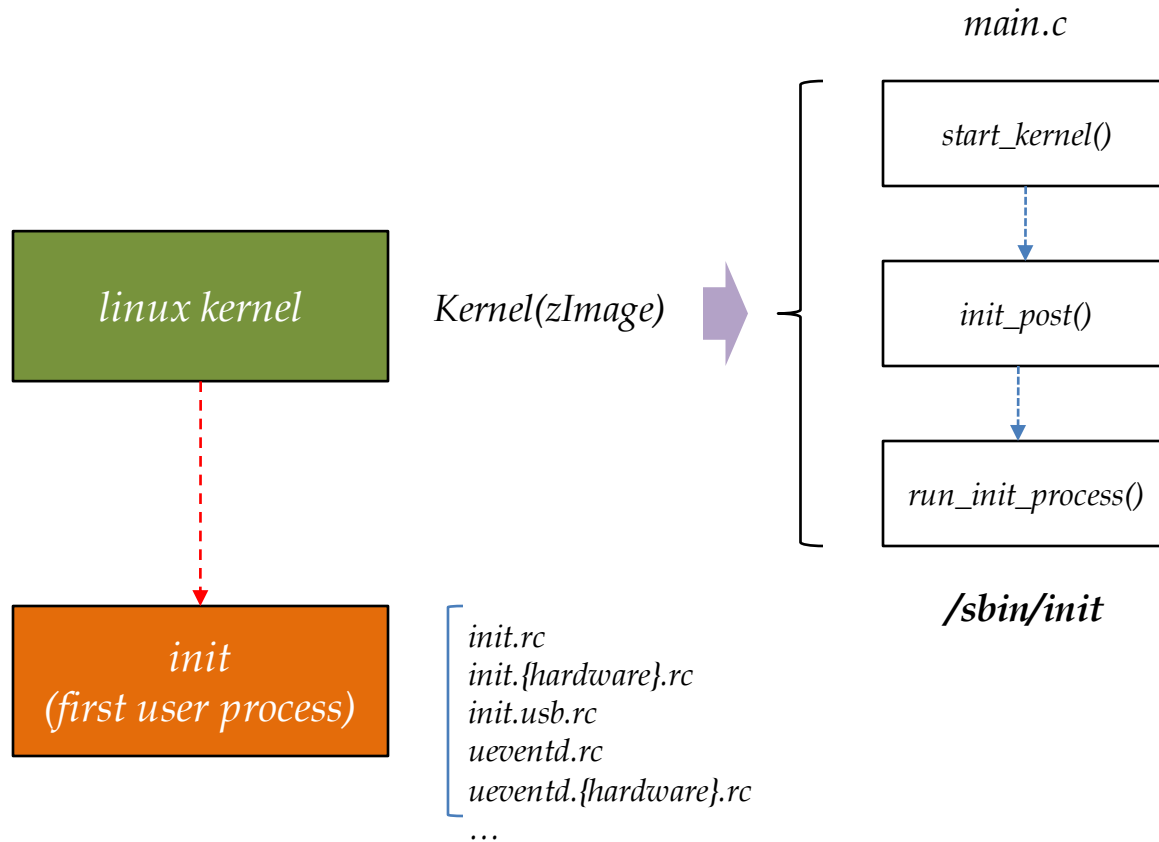
7. Jelly Bean Android Boot Flow(1)



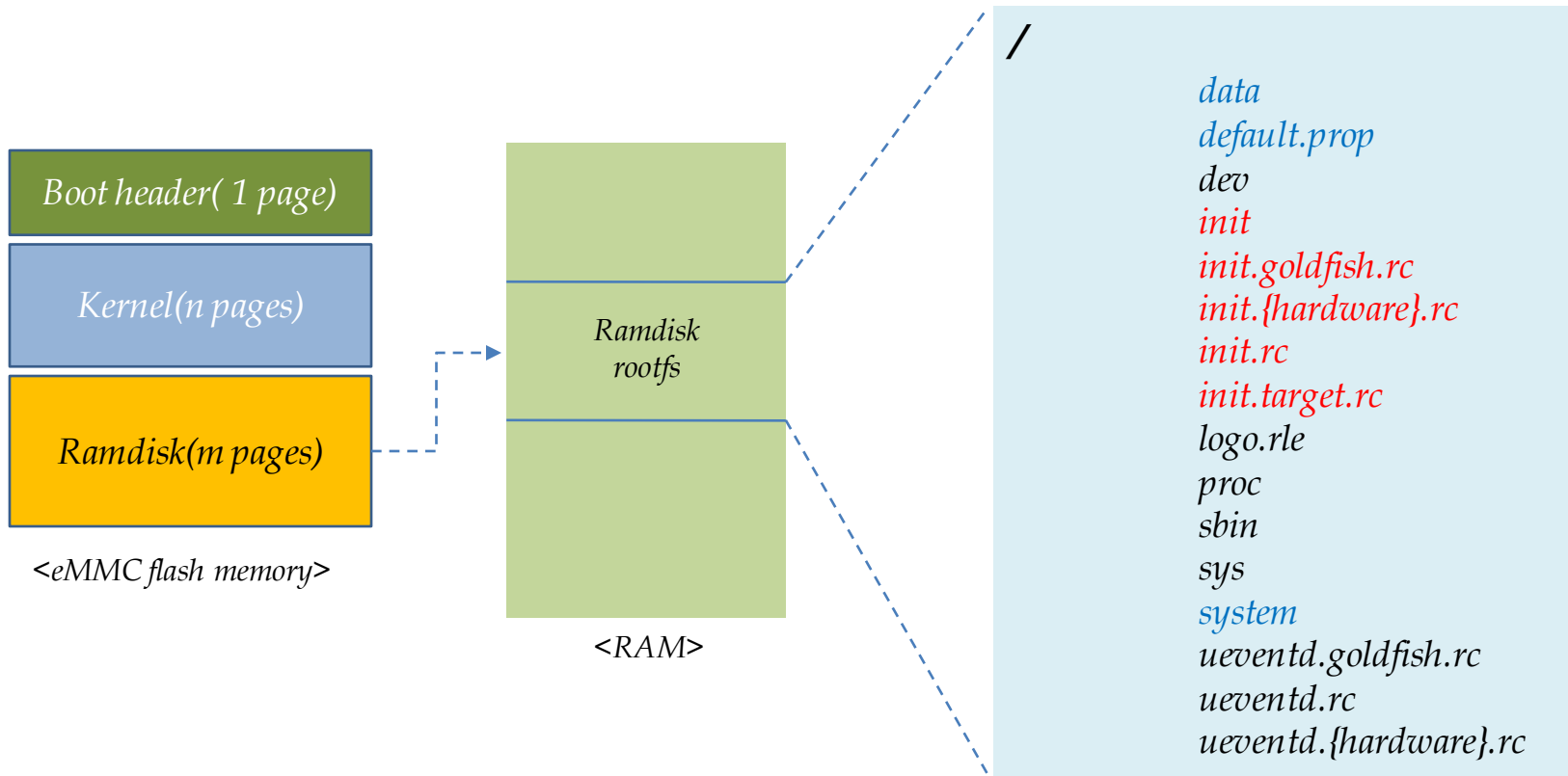
7. Jelly Bean Android Boot Flow(2)



7. Jelly Bean Android Boot Flow(3)



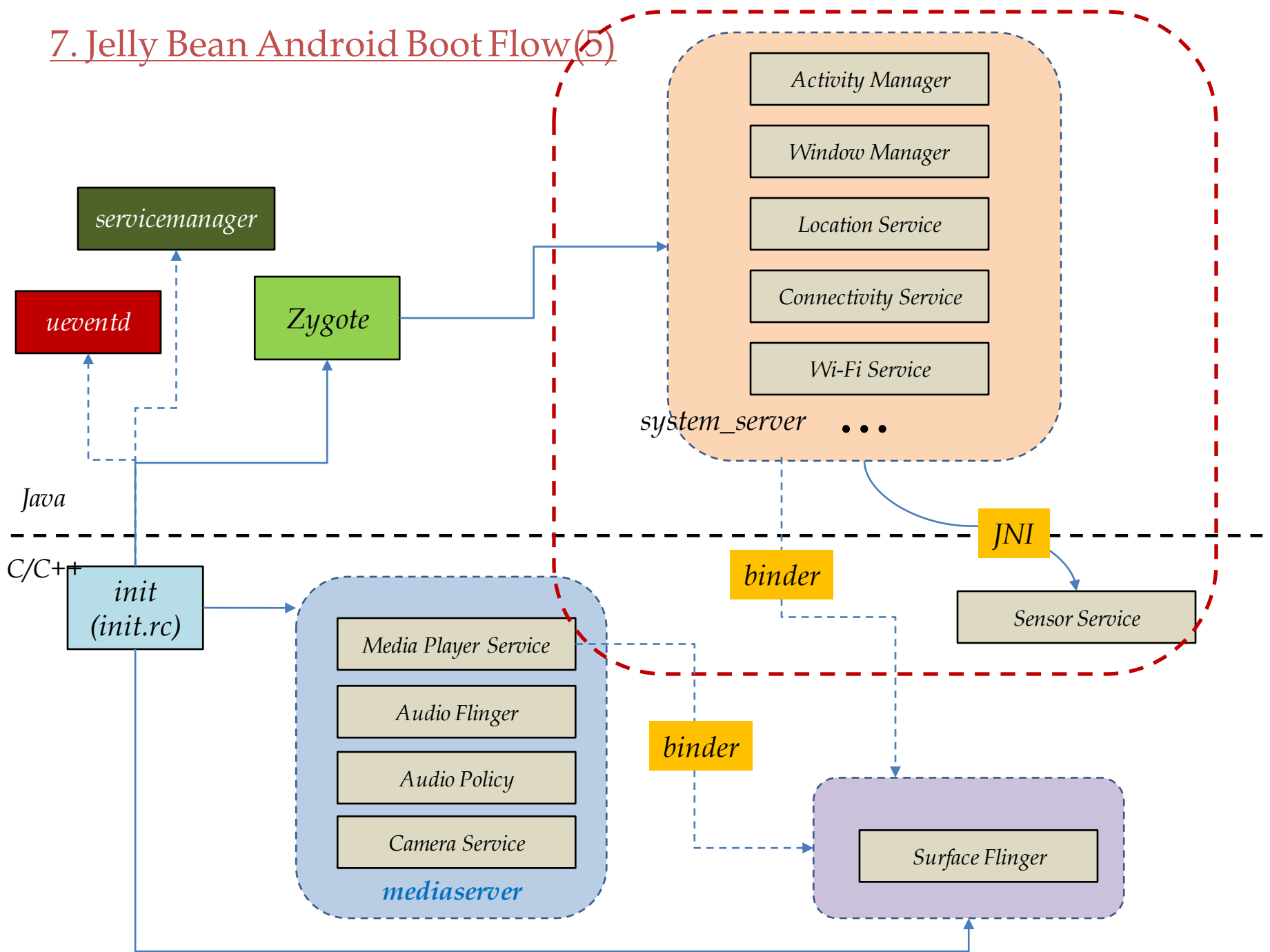
7. Jelly Bean Android Boot Flow(4)



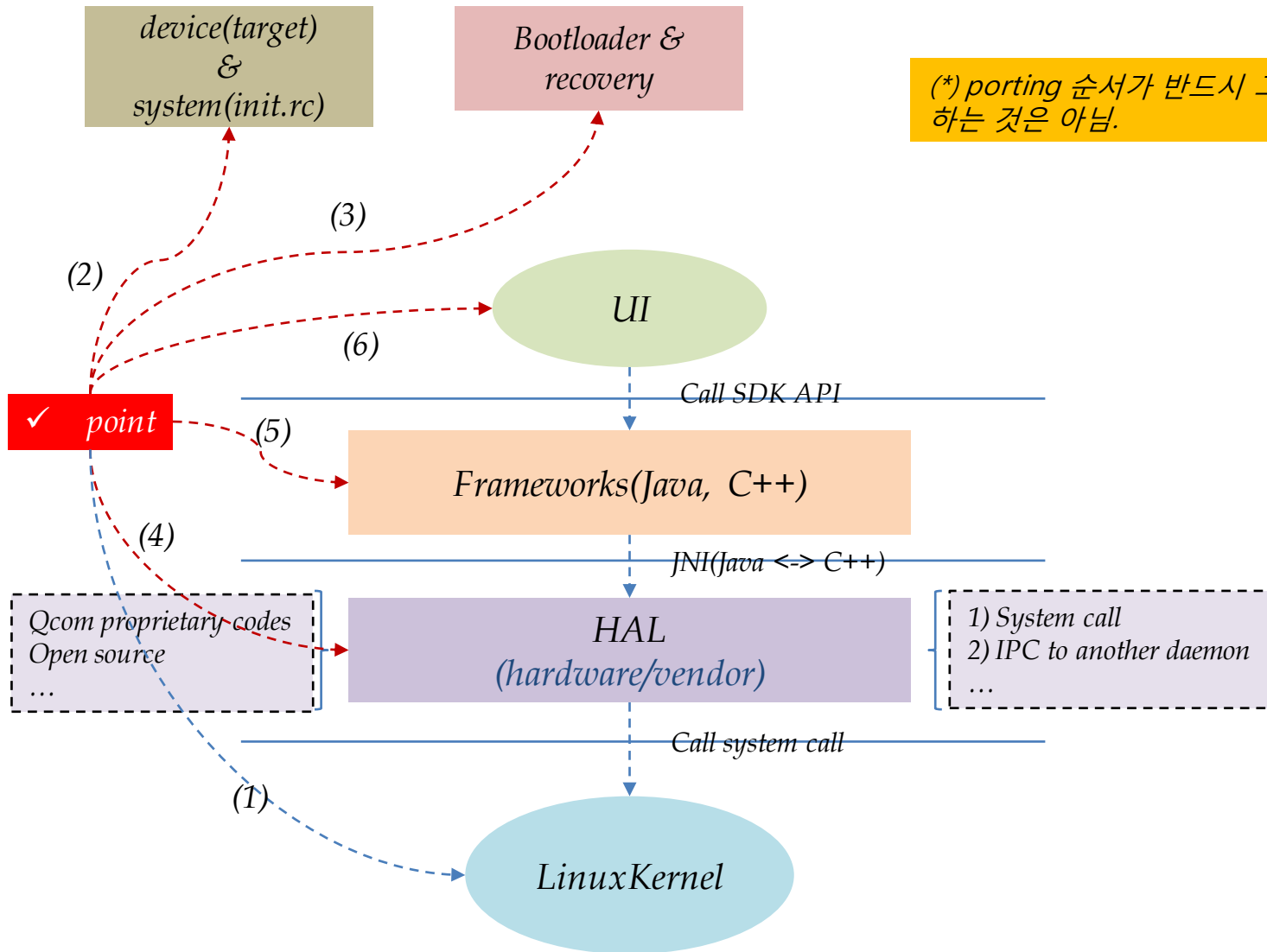
```
# mount -o remount,rw -t ext4 /dev/block/mtdblockX /system  
# mount -o remount,rw -t ext4 /dev/block/mtdblockX /data
```

(*) *rootfs* 이외의 *file system*은 위와 같은 형태로 *mount* 가능

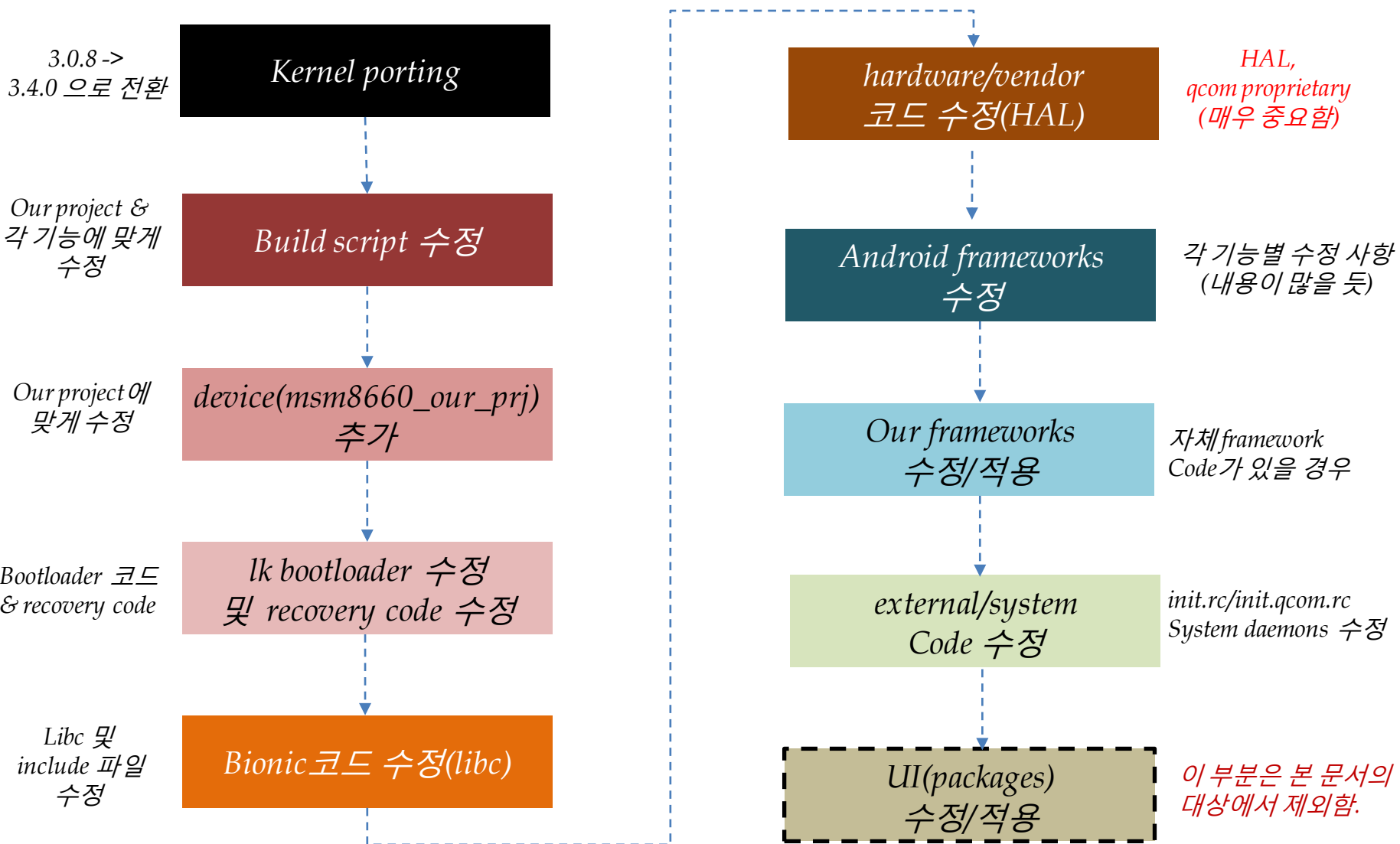
7. Jelly Bean Android Boot Flow (5)



8. Jelly Bean BSP Porting Scope(1) - *Android/1*



8. Jelly Bean BSP Porting Scope(1) - Android/2



8. Jelly Bean BSP Porting Scope(2) - Target Board 파일 분석

```
# find device/ build/target/ vendor/ -name AndroidProducts.mk  
← build/envsetup.sh
```

core/config.mk

msm8660_surf.mk

BoardConfig.mk

→
Product-specific compile-time
definitions

device/qcom/msm8660_surf/*

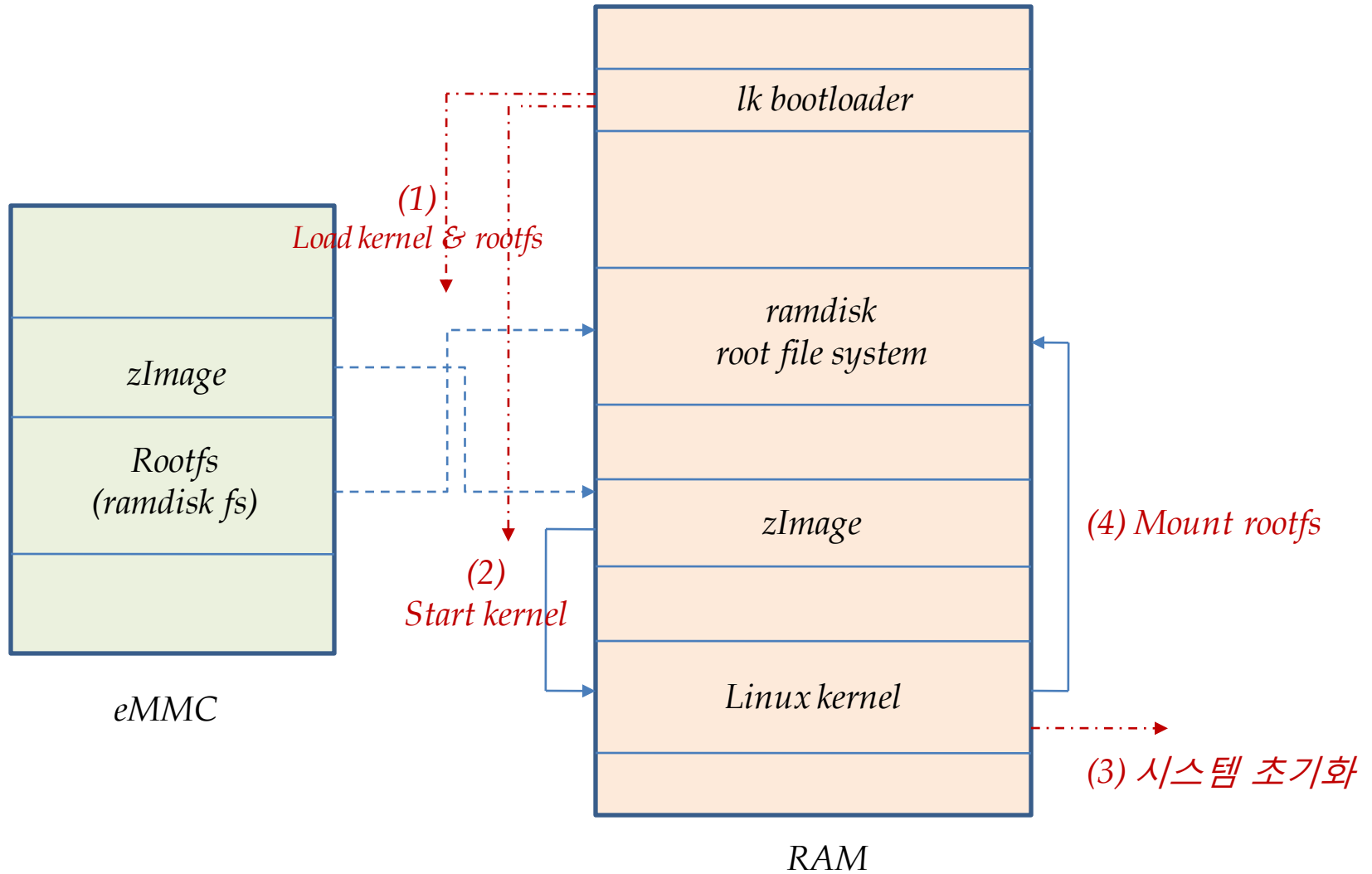
device/qcom/msm8660_surf/AndroidProducts.mk

AndroidBoard.mk

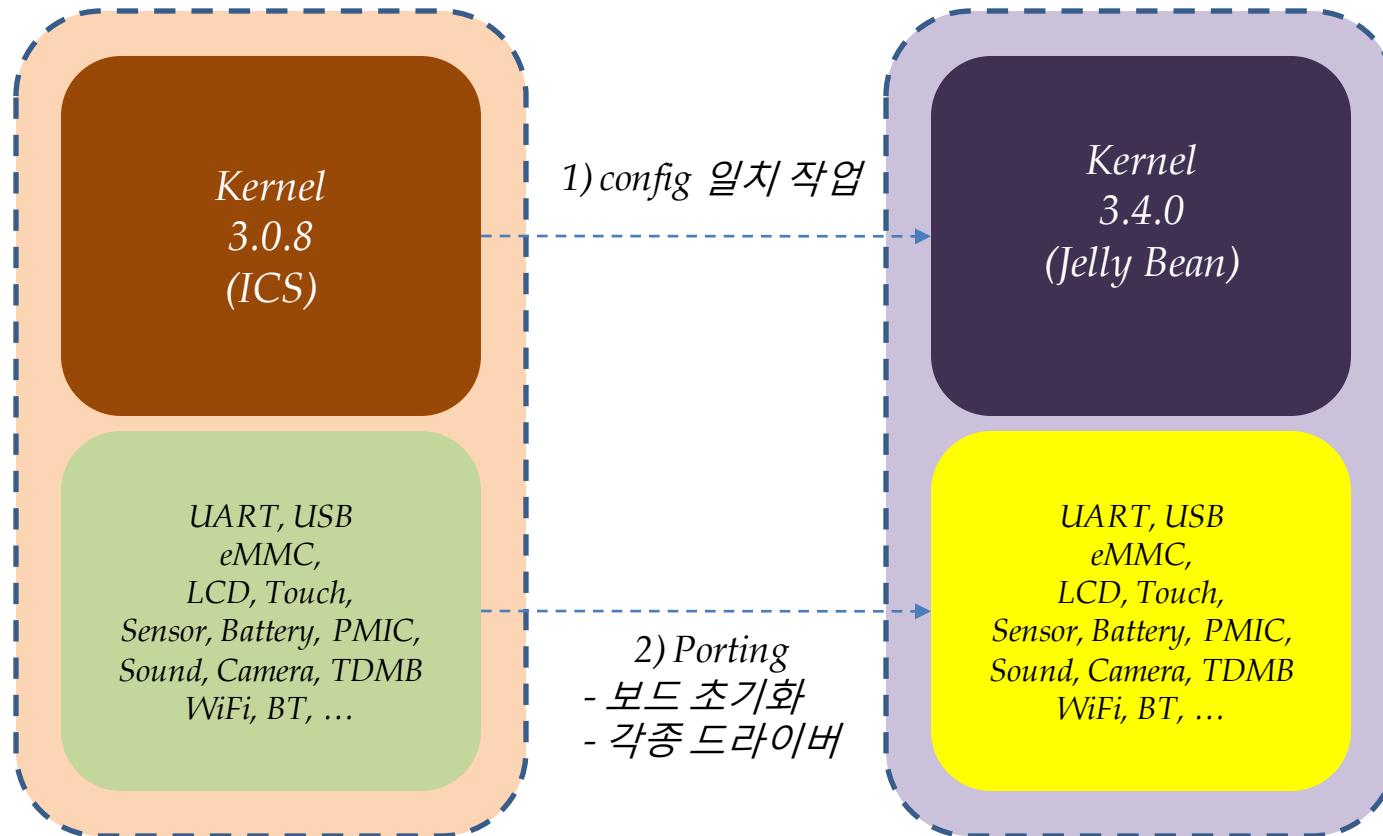
-
- 1) include AndroidBoot.mk
 - 2) include AndroidKernel.mk
 - 3) Key mapping
 - 4) 기타 환경 파일 정의

(* build 환경 설정 후, bootloader(AndroidBoot.mk)를 Build하고,
이어서 linux kernel(AndroidKernel.mk)을 build한다.

8. Jelly Bean BSP Porting Scope(3) - lk bootloader



8. Jelly Bean BSP Porting Scope(4) - Linux Kernel/1



(*) 여기서 말하는 포팅은 ICS kernel에 대해 신규로 추가한 모든 내용(디바이스 드라이버 등)을 Jelly Bean kernel 기반으로 옮기는 작업을 뜻한다.

(*) 따라서, 1차적으로 kernel configuration을 일치시키는 작업을 진행해야 하며, 이후 신규로 추가한 코드 부분을 Jelly Bean kernel로 옮기는 작업을 진행해야 한다.

8. Jelly Bean BSP Porting Scope(4) - Linux Kernel/2

0) configuration 일치

1) 보드 초기화 → *arch/arm/mach-msm/**

2) 각종 device drivers → *drivers/**

Platform drivers

(*drivers/...*)

→ Runtime에 platform driver를 구동시키는 역할

Some device drivers

Platform device

(*board-msm8x60*.c*)

→ 부팅시, Platform device를 install하는 역할

Sub system codes

- reset/restart

- monitoring

- smd & smem

(communication with modem)

- firmware loading

msm core device codes

(*devices-msm8x60.c*)

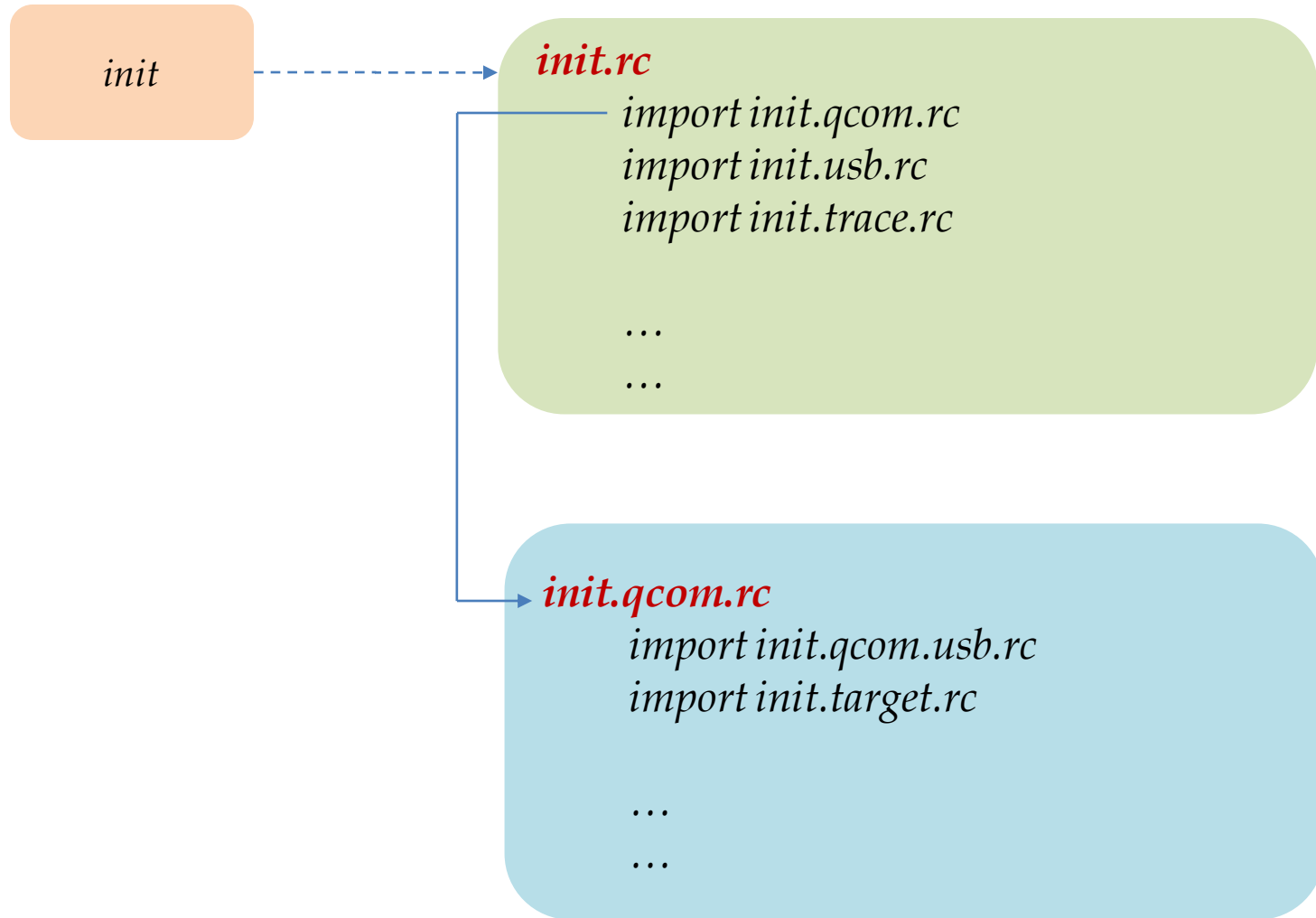
→ Platform device를 정의하는 역할

*gpio, irq, regulators,
memory, io*

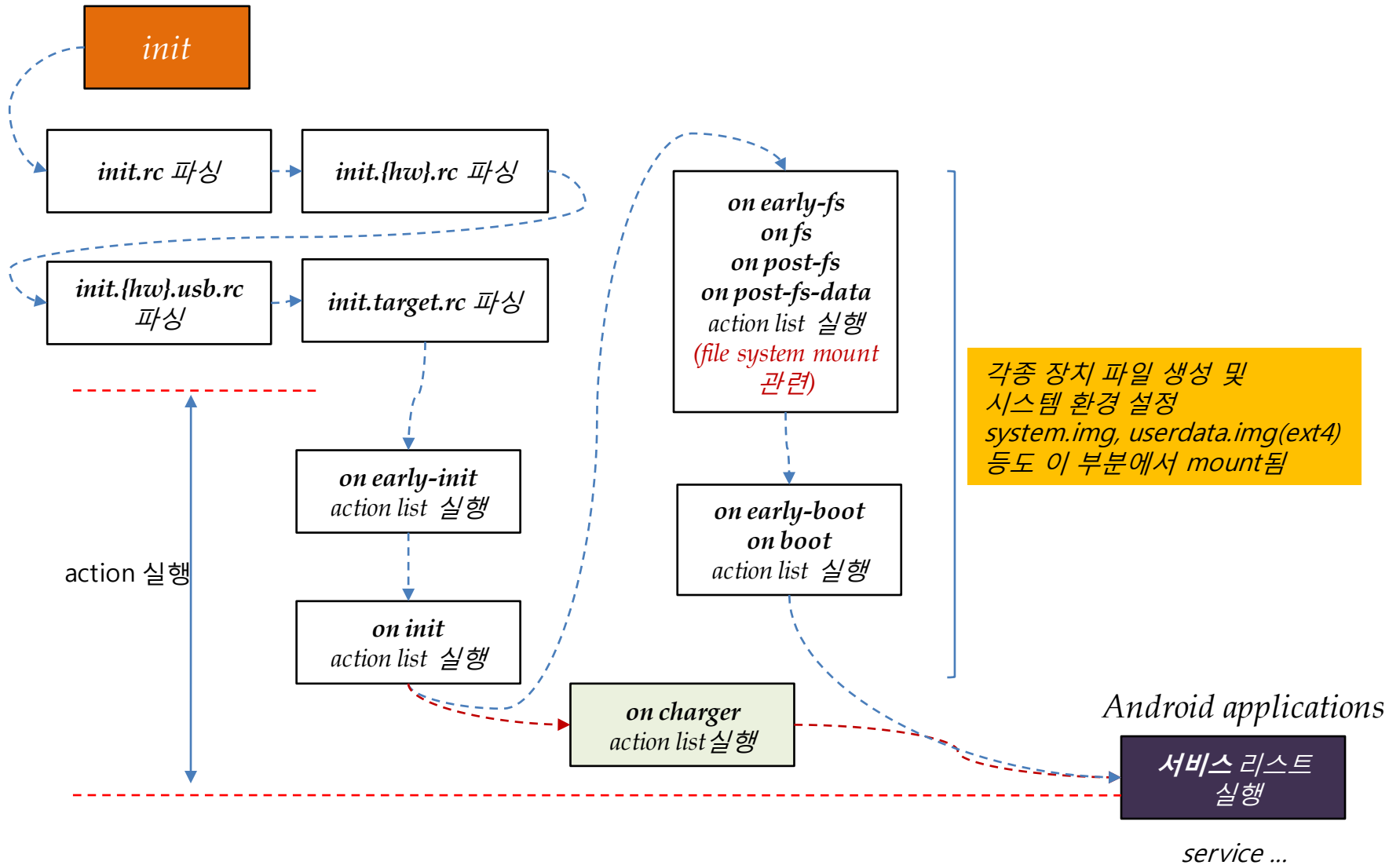
*Low-level clock/register
functions
(`__raw__`{read,write}, clk*)*

watchdog, timer, debug system

8. Jelly Bean BSP Porting Scope(5) – *init* & *init.rc/1*



8. Jelly Bean BSP Porting Scope(5) – *init* & *init.rc/2*



9. BSP Porting(1) - 1 단계

1) *config* 조정하기(일치)
(*arch/arm/configs*)

2) *board* 초기화 코드 일치

- *board-msm8x60.c*
- *devices-msm8x60.c*
- *gpiomux-8x60.c*
- *LCD panel & framebuffer, sound*
- ...
- *clock-8x60.c*

각종 장치 초기화

- 1) *Clock* 초기화
- 2) *Bus* 초기화
- 3) *eMMC* 초기화
- 4) *UART* 초기화
- 5) *LCD/framebuffer*
- 6) *I2C/SPI* 장치 초기화
- 7) *Sound* 초기화
- 8) ...

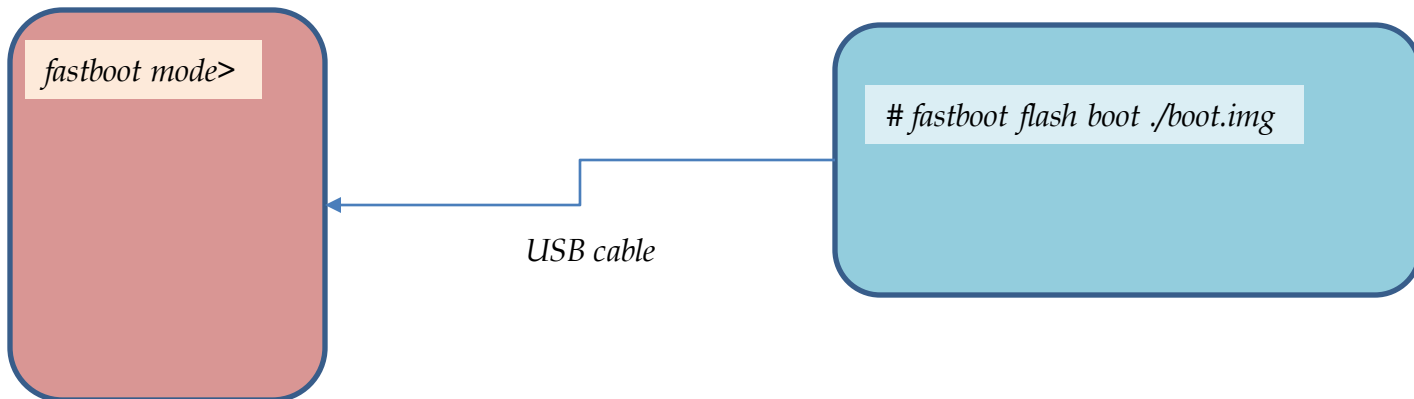
3) *lcd/display driver* porting

4) *Booting test(with fastboot)*

next page

9. BSP Porting(2) - 2 단계: fastboot로 image write 하기

- `# adb reboot-bootloader` ← *fastboot mode*로 전환(혹은 시스템에서 정의한 key 조합으로도 진입 가능)
- `# fastboot flash boot ./boot.img`
- `# fastboot flash system ./system.img`
- `# fastboot erase userdata`
- `# fastboot flash userdata ./userdata.img`
- `# fastboot flash persist ./persist.img`
- `# fastboot flash cache ./cache.img`



9. BSP Porting(3) - 3 단계

5) *Debugging*
→ *kernel panic* 등 다양한 문제 해결 과정 필요

6) *USB gadget driver porting*
→ *adb*가 동작하도록 ...

7) *mach-msm/ 나머지 부분 porting*
- *mdm*
- *sub system restart*
- *Reset*
→ *Power off* 시 정상 동작하도록 ...

8) *Battery/Charger driver porting*
→ 충전이 안되어 *booting*이 안될 경우 대비

9. BSP Porting(4) - 4 단계: android target porting

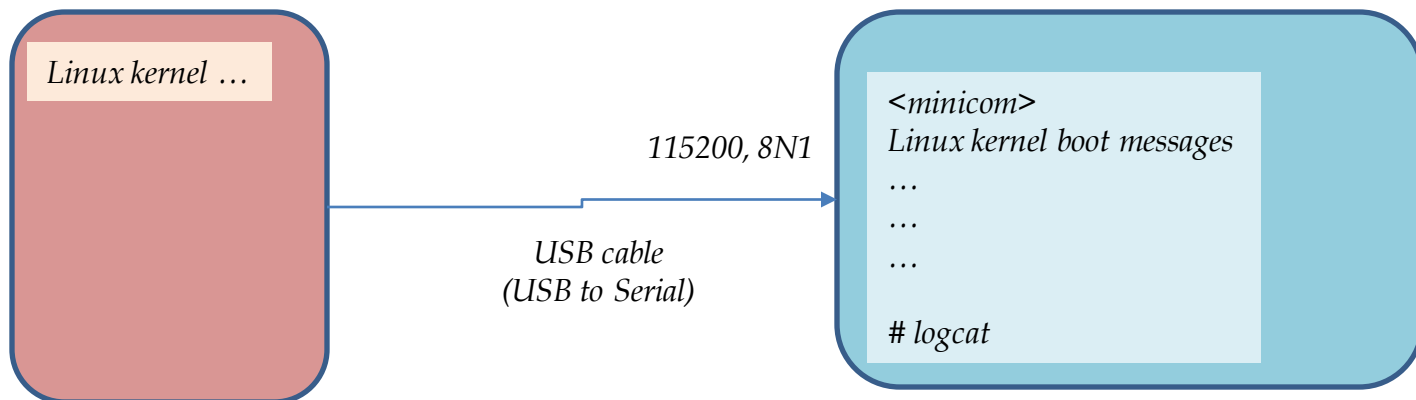
- *device/qcom/msm8660_surf/AndroidBoard.mk*
- *device/qcom/msm8660_surf/BoardConfig.mk*
- *device/qcom/msm8660_surf/init.qcom.mdm_links.sh*
- *device/qcom/msm8660_surf/init.target.rc*
- *device/qcom/msm8660_surf/msm8660_surf.mk*
- *device/qcom/msm8660_surf/recovery.fstab*
- *device/qcom/msm8660_surf/*.kl*
- *device/qcom/msm8660_surf/**

- *device/qcom/common/rootdir/etc/init.qcom.rc*
- *device/qcom/common/rootdir/etc/init.qcom.usb.rc*
- *device/qcom/common/rootdir/etc/ueventd.qcom.rc*
- *device/qcom/common/rootdir/etc/**

- *system/core/rootdir/init.rc*
- *system/core/rootdir/ueventd.rc*

9. BSP Porting(5) - 5 단계: debugging

- 1) console
 - minicom - 115200, 8N1
 - 2) adb
 - adb shell
 - logcat 으로 문제점 debugging
- ➔ Board bring-up 단계에서는 모든 기능을 porting 한 것이 아니므로, 의외의 곳에서 시스템이 죽을 수 있음(주요 대상: surfaceflinger, system_server, mediaserver 등)



9. BSP Porting(6) – Kernel Boot Messages

```
<6>[ 0.000000] Booting Linux on physical CPU 0
<6>[ 0.000000] Initializing cgroup subsys cpu
<5>[ 0.000000] Linux version 3.4.0-perf-g49f91a2-dirty (chungghan.yi@gmail.com) (gcc version 4.6.x-google 20120106
(prerelease) (GCC) ) #26 SMP PREEMPT Fri Oct 5 10:52:50 KST 2012
<4>[ 0.000000] CPU: ARMv7 Processor [510f02d2] revision 2 (ARMv7), cr=10c5387d
<4>[ 0.000000] CPU: PIPT / VIPT nonaliasing data cache, VIVT ASID tagged instruction cache
<4>[ 0.000000] Machine: SLOWBOOT SLOWBOOT BOARD MSM8X60
<6>[ 0.000000] memory pool 0 (start 38000000 size 600000) initialized
<6>[ 0.000000] memory pool 1 (start 38600000 size 3802000) initialized
<6>[ 0.000000] memory pool 3 (start 79400000 size 6c00000) initialized
<4>[ 0.000000] Memory policy: ECC disabled, Data cache writealloc
<6>[ 0.000000] socinfo_init: v6, id=71, ver=2.0, raw_id=1329, raw_ver=1, hw_plat=0, hw_plat_ver=65537
<6>[ 0.000000] accessory_chip=58 hw_plat_subtype=0
<7>[ 0.000000] On node 0 totalpages: 212992
<7>[ 0.000000] free_area_init_node: node 0, pgdat c0cc7b80, node_mem_map c18eb000
<7>[ 0.000000] Normal zone: 992 pages used for memmap
<7>[ 0.000000] Normal zone: 0 pages reserved
<7>[ 0.000000] Normal zone: 104992 pages, LIFO batch:31
<7>[ 0.000000] HighMem zone: 1052 pages used for memmap
<7>[ 0.000000] HighMem zone: 105956 pages, LIFO batch:31
<6>[ 0.000000] allocating 30175232 bytes at c7e00000 (48000000 physical) for fb
<6>[ 0.000000] PERCPU: Embedded 9 pages/cpu @c9aca000 s15296 r8192 d13376 u36864
<7>[ 0.000000] pcpu-alloc: s15296 r8192 d13376 u36864 alloc=9*4096
<7>[ 0.000000] pcpu-alloc: [0] 0 [0] 1
<4>[ 0.000000] Built 1 zonelists in Zone order, mobility grouping on. Total pages: 210948
<5>[ 0.000000] Kernel command line: console=ttyDCC0,115200,n8 console=ttyHSL0,115200,n8 androidboot.hardware=qcom
kgsl.mmctype=gpmumu vmalloc=512M uart_console=disable slowboot.rev=rev_b slowboot.hreset=off slowboot.reboot=pwroff
slowboot.lcd=off slowboot.batt_info=<null> slowboot.pwron=usb_chg slowboot.reset=rst_etc slowboot.usb_cable=normal
kcal= 0 0 0 0 0 mdm_force_dump_enabled idv2 androidboot.emmc=true androidboot.serialno=64005dc3 slowboot.signed_im
age=true androidboot.baseband=svlte2a
<6>[ 0.000000] BOARD : SLOWBOOT rev_b
<6>[ 0.000000] BOARD : SLOWBOOT target 2
<6>[ 0.000000] usb_cable_info : normal (8)
<6>[ 0.000000] ####kcal=, r=0, g=0, b=0 sign=0,0,0
<6>[ 0.000000] PID hash table entries: 2048 (order: 1, 8192 bytes)
<6>[ 0.000000] Dentry cache hash table entries: 65536 (order: 6, 262144 bytes)
<6>[ 0.000000] Inode-cache hash table entries: 32768 (order: 5, 131072 bytes)
<6>[ 0.000000] Memory: 44MB 788MB = 832MB total
<5>[ 0.000000] Memory: 794416k/794416k available, 168144k reserved, 428032k highmem
<5>[ 0.000000] Virtual kernel memory layout:
<5>[ 0.000000] vector : 0xffff0000 - 0xffff1000 ( 4 kB)
<5>[ 0.000000] fixmap : 0xffff0000 - 0xffffe000 ( 896 kB)
<5>[ 0.000000] vmalloc : 0xdf800000 - 0xff000000 ( 504 MB)
<5>[ 0.000000] lowmem : 0xc0000000 - 0xdf000000 ( 496 MB)
<5>[ 0.000000] pkmap : 0xbfe00000 - 0xc0000000 ( 2 MB)
```

9. BSP Porting(7) – *ps result(busybox ps)*

```
100 0          0 SW< [krfcommd]
101 0          0 SW< [msm-cpufreq]
102 0          0 SW< [rq_stats]
103 0          0 SW< [deferwq]
104 0          0 SW< [fsa8008]
105 0          0 SW [irq/639-fsa8008]
106 0          0 SW [irq/640-fsa8008]
107 0          376 S  /sbin/ueventd
108 0          0 SW [jbd2/mmcblk0p26]
109 0          0 SW< [ext4-dio-unwrit]
110 0          0 SW [jbd2/mmcblk0p20]
111 0          0 SW< [ext4-dio-unwrit]
112 0          0 SW [jbd2/mmcblk0p29]
113 0          0 SW< [ext4-dio-unwrit]
114 0          0 SW [jbd2/mmcblk0p28]
115 0          0 SW< [ext4-dio-unwrit]
116 0          0 SW [jbd2/mmcblk0p12]
117 0          0 SW< [ext4-dio-unwrit]
118 0          0 SW [jbd2/mmcblk0p27]
119 0          0 SW< [ext4-dio-unwrit]
120 0          0 SW [jbd2/mmcblk0p23]
121 0          0 SW< [ext4-dio-unwrit]
123 1000       916 S  /system/bin/servicemanager
125 0          4184 S  /system/bin/vold
128 0          10040 S  /system/bin/netd
129 0          1212 S  /system/bin/debuggerd
133 1019       8884 S  /system/bin/drmserver
134 1013       29740 S  /system/bin/mediaserver
135 1002       1428 S  /system/bin/dbus-daemon --system --nofork
136 0          928 S  /system/bin/installd
138 1017       1944 S  /system/bin/keystore /data/misc/keystore
144 2000       844 S  /system/bin/sh
145 9999       908 S  /system/bin/rmt_storage
146 0          8892 S  /system/bin/time_daemon
147 0          5504 S  /sbin/adbd
170 1001       4048 S  /system/bin/qmuxd
173 1001       5204 S  /system/bin/qmiproxy
176 0          4148 S  /system/bin/netmgrd
903 0          5264 S < /system/bin/mpdecision --no_sleep --avg_comp
983 1000       6096 S  /system/bin/mm-pp-daemon
1238 0         440m S  zygote /bin/app_process -Xzygote /system/bin --zygot
1239 1000       74312 S  /system/bin/surfaceflinger
1279 1000       554m S  system_server
1430 10042     471m S  {ndroid.systemui} com.android.systemui
1487 10012     453m S  {d.process.media} android.process.media
1492 10019     452m S  {putmethod.latin} com.android.inputmethod.latin
1519 1001     460m S  {m.android.phone} com.android.phone
1530 10020     482m S  {ndroid.launcher} com.android.launcher
```


Thanks a lot !



Slow Boot